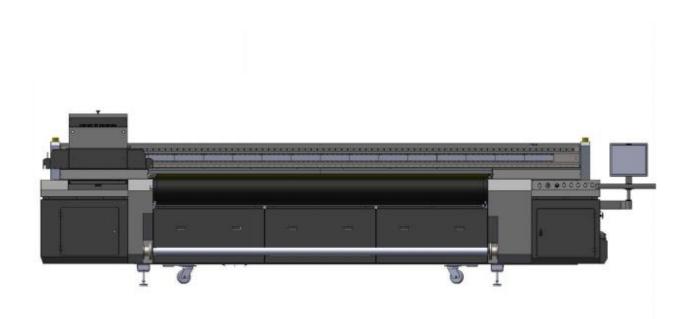


# 3200 Hybrid UV printer installation instruction

# HT3200-UV\_K





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#### **FOREWORD**

UV printers are composed of precision mechanical and electrical parts. This manual is made for helping users to better use this product.

The writing purpose of this manual is intended to allow the user to safe and efficient use of machines in a proper environment. Be sure to read the instructions carefully before using this machine.

Please kindly understand the information changed due to the upgrade of the machine without prior notice. If you have any questions about the use of the machine. Please contact the local agent or our aftersales service staff.



## Safety Precautions

# 1. Indications of symbols

| ****     | This symbol indicates the failures to be caused                             |
|----------|---|
|          | by the ignorance of misunderstanding of the                                 |
|          | instruction may probably lead to equipment                                  |
|          | damage or personal injury   |
|          | This symbol indicates the possible risk of the given operation              |
| 0        | This symbol indicates the improper operation to be strictly prohibited      |
|          | This symbol indicates the proper protections needed for the given operation |
| <b>\</b> | This symbol indicates the reference part of this manual                     |
| Ö        | This symbol indicates the useful tips                                       |

# 2. Precautions of operations



#### **Working environment**



Never use the printer in a non-ventilated or stuffy workplace, or it may lead to toxic hazards to operators. A ventilator is always a necessity.



Do not use the machine in the explosive atmosphere.



The printer is a precision equipment and should always avoid strong impact or shake in any process of loading, installation and operation, or it may result in equipment damage.



Avoid setting foot or heavy items placed on the printer or it may result in equipment damage.



See product introduction - detailed parameters

#### Forbidden modification



Any unauthorized alteration is strictly prohibited, or it might cause parts malfunction or damage to the printer.



Any disassemble or replacement of the parts and cables is strictly prohibited in the state of power-on.

## **Electricity**



Please supply the printer with rated voltage and frequency, improper power input may cause functional abnormality or damage to the printer.



Avoid any liquid spilled on the electronic parts or it may result in parts malfunctions.



Verify that the printer is properly ground wired or it might cause some electric shock risks.

## **UV** light protection



Avoid continuous eye-contact with the ultra-violets of the lamp.



Wear an anti-UV goggles when the printer is working to protect the operator from accidental direct eye-contact with the UV light.



#### Operator awareness



Any disassemble or replacement of the parts and cables is strictly prohibited in the state of power-on



Avoid any body contact with the locomotion parts in the process of printer working, or it may lead to equipment breakdown or personal injury.



Wear rubber gloves to avoid chemical liquid spilled on human body.



Flush with adequate purified water immediately if accident happened and see a doctor afterwards.

#### Ink store



Keep the chemical consumables away from non-qualified individuals and stored according to the specific instructions.

#### Deposing waste ink and liquid



The treatment of the waste chemicals should abide by local environment regulations.

### **Emergency reaction**



Always remember to press the scram stop at any emergency, and the printer should not be activated until all the malfunctions are settled.



Introduction

#### 1.Printer brief introduction

The model of HT3200UV-D-K10 Kyocera Hybrid UV inkjet printer is highly cost-effective equipment specially designed for commercial printing enterprises.

#### 2. Printer Features

With the self-R&D ability that enables constant advancement.

Professional assembly crafts guarantee the perfect qualities.

Adopt high quality components (EGUS chain, linear motor)

Ironic beam plus dual lead rails assembly on X-directional mechanical structure enables the carriage to run stably.

High precision linear encoder strip for the positioning of the carriage.

Optical fiber with a maximum transmitting speed of 1.25Gb/S and zero-interference ability.

Industrial PCIE data transmitting interface with excellent proof to electric-magnetic interference.

Automatic head height adjustment enables the head height adjustable to different media thickness of 0-50mm.

A dual lead screw on the Y-directional mechanical structure guarantees the basis of the stable and high precision stepping movement.

Anti-crashing attachment can effectively reduce the head-strike risks.

Double-class ink-heating automatic control guarantees the optimum viscosity of ink for print head continuously discharging.

Special negative pressure tank for keeping the pressure in the state of main power-off.

More intuitive and user-friendly operating interface.

With the ability to 24hoursX7days continuous running of commercial printing production.

## 3. Printer configurations

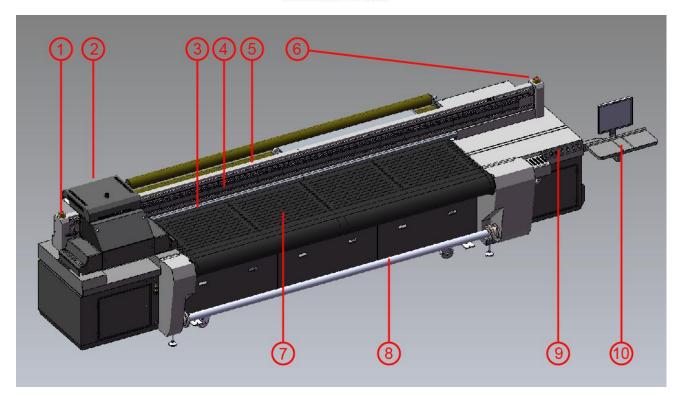


| Model                  | HT3200UV_D  |  |  |
|------------------------|---|--|--|
| Printhead<br>type      | Kyocera high-performance drop-on-demand piezo heads   |  |  |
| Printhead array        | 5-10PCS   |  |  |
| Maximum resolution     | 363*3600 DPI  |  |  |
| Print size             | Up to 3.2m of printing width  |  |  |
| Media type             | Rigid and flexible printing media   |  |  |
| Printed thickness      | 0-50mm  |  |  |
| Applications           | glass, acrylic, wooden board, ceramic tile, metals, PVC board, corrugated board, plastic board, etc |  |  |
| Ink type               | Environmental-friendly UV ink (non-VOC)   |  |  |
| Color mode             | Lc, Lm, K, C, M, Y, W   |  |  |
| Support file           | Adobe Postscript Level 3、PDF、 JPEG、TIFF、EPS、 AI   |  |  |
| Support RIP            | Caldera/Onyx  |  |  |
| PC system              | Windows7  |  |  |
| NET. Weight            | 2350kg  |  |  |
| Dimension              | <u>5530x1550x1320</u>   |  |  |
| Power consumption      | 8kW, 20A  |  |  |
| Power requirement      | Three phase 380v,50Hz   |  |  |
| Environment conditions | Temperature: 18°C ~ 30°C (64°F ~ 86°F)  |  |  |
|                        | Humidity: 30% ~ 70%   |  |  |
| Certificate            | CE, FCC, ETL  |  |  |

# **4.Structure Diagrams**

# 4.1 Front view of the printer



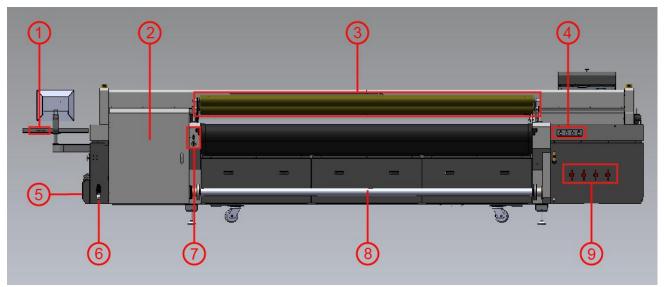


- 1. Emergency Stop Button Front Left
- 2. Carriage
- 3. Automatic Media Alignment
- 4. Linear Motor Rail
- 5. Beam

- 6. Emergency Stop Button Front Right
- 7. Printing Platform
- 8. Media Take up Roller
- 9. Electric Control Panel Front
- 10. Computer Monitor Assembly

## 4.2 Rear view of the printer



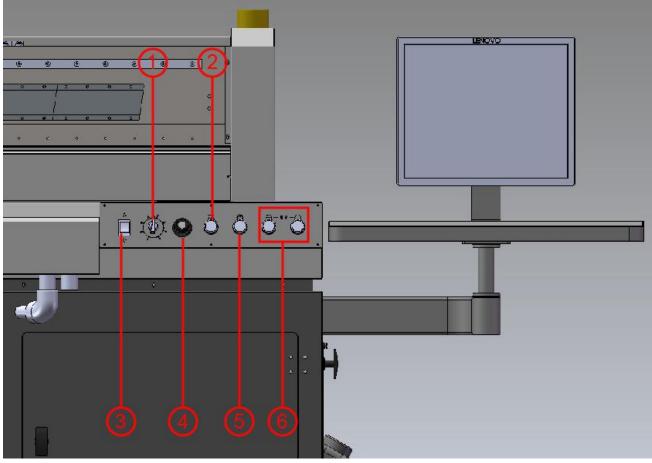


- 1. USB 2.0 Extension Port
- 2. Electric Box
- 3. Media Guide Rollers
- 4. Electric Control Panel Rear
- 5. Ink Main Tank Box

- 6. Main Power Switch
- 7. Media Feeding Control
- 8. Media Feeding Roller
- 9. Suction Control Area



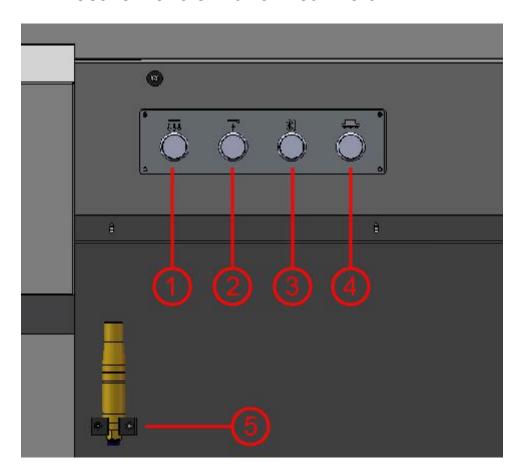
**4.3 Electric Control Panel Front Right** 



- Media Take-up Speed Control Switch
- 2. Suction Button
- Media Take-up Direction ControlSwitch
- 4. Suction Power Control Switch
- 5. Start Button
- UV Mercury Lamp Control(Not For LED Lamp)



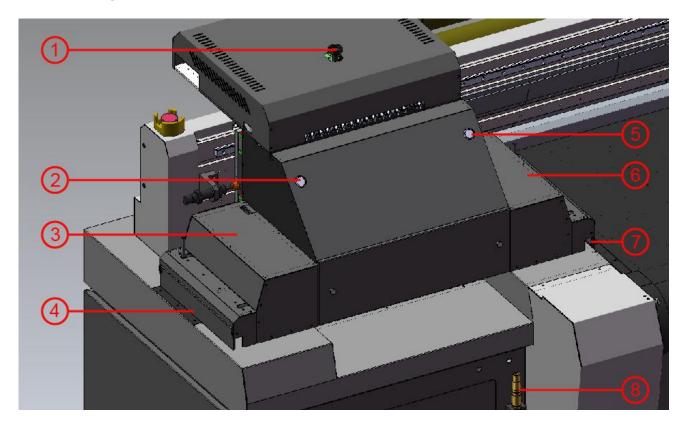
## **4.4 Electric Control Panel Rear Left**



- 1. Suction Button
- Automatic Media Alignment Button
- 3. Media Guide Roller Button
- 4. Print Button
- 5. Air Gun



## 4.5 Carriage Component

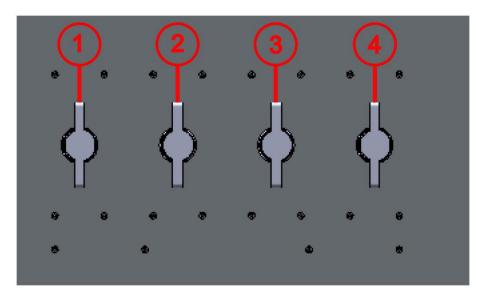


- 1. Carriage height manual-adjust knob
- 2. Color Purge Button
- 3. LED Lamp Assembly Left
- 4. Anti-crash Assembly Left

- 5. White Purge Button
- 6. LED Lamp Assembly Right
- 7. Anti-crash Assembly Right
- 8. Air Gun

## 4.6 Suction area control

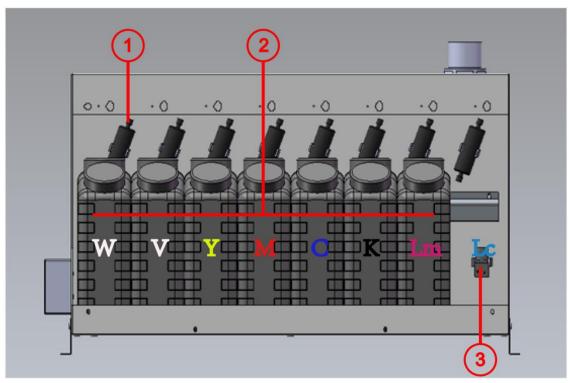




- 1. Suction Area 1
- 2. Suction Area 2

- 3. Suction Area 3
- 4. Suction Area 4

## 4.7 ink system diagram

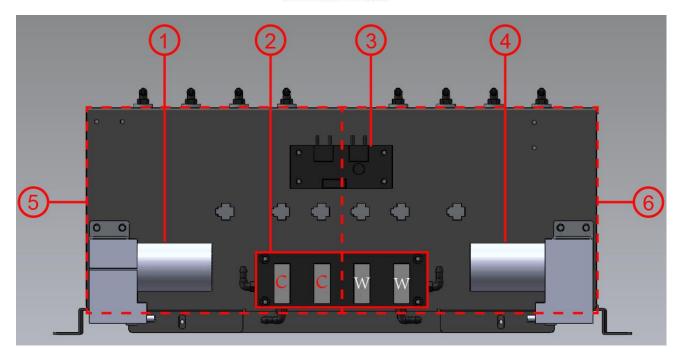


1. Ink Filter

- 2. Ink Main Tank
- 3. Ink Pump

## 4.8 Negative pressure system diagram





- 1. Color Negative Pressure Pump
- 2. Solenoid Valve
- 3. Negative Pressure Board

- 4. White Negative Pressure Pump
- 5. Color Negative Pressure Tank
- 6. White Negative Pressure Tank

## 4.9 Electrical System Diagram





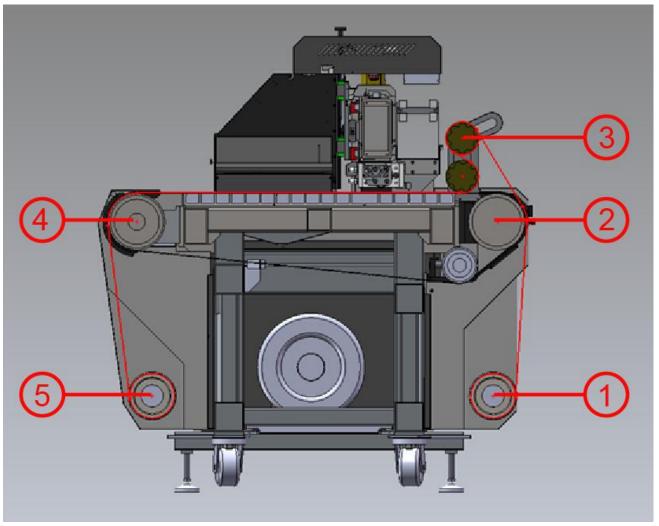


- 1. DC24v Terminal Block
- 2. Relay For Heating
- 3. Relay For Blower
- 4. Relay For Anti-static
- 5. AC Contactor
- 6. AC220V Terminal Block
- 7. Fuses For AC220V
- 8. Filter
- 9. Fuses For DC24V
- 10. JBK Control Transformer
- 11. External Device Control Board
- 12. Suction Control Board

- 13. Negative Pressure Control Board For Suction
- 14. Blower Frequency Converter
- 15. X Linear Motor Driver
- 16. Y Servo Driver
- 17. Conveyor Correct Motor Driver
- 18. 27V Power Supply
- 19. Toroidal Transformer For Take-up Roller
- 20. Toroidal Transformer For Feeding Roller
- 21. 24V Power Supply



## 4.10 media loading diagram

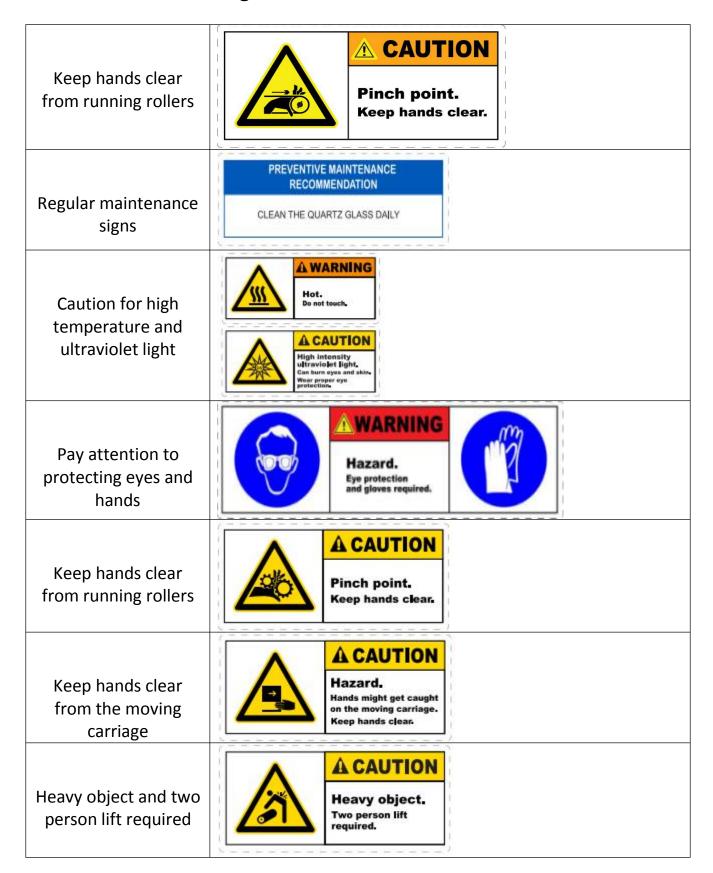


- 1. Feeding roller
- 2. Driven roller
- 3. Media guide rollers

- 4. Driving roller
- 5. Take-up roller



## 4.11 device label diagram





#### Printer installation

## 1. Environment requirements

Field dimension at least 7.5\*5m

Without excessive dust and other pollutants

Temperature: 18C ~ 30 °C (64F ~ 86F)

Humidity: 30%~70%RH

Avoid direct sunlight

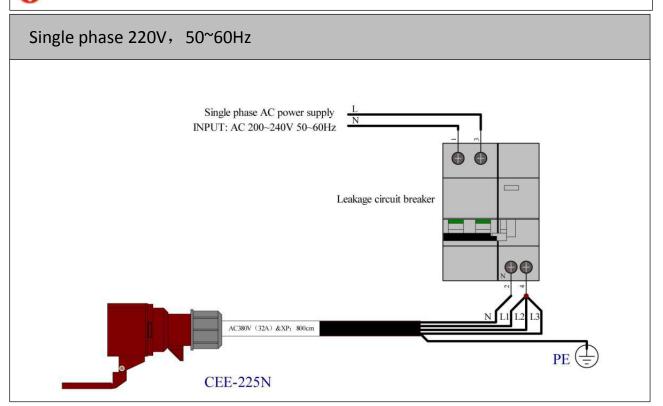
Properly ventilated

Max input power 8.3kW, max current 20A

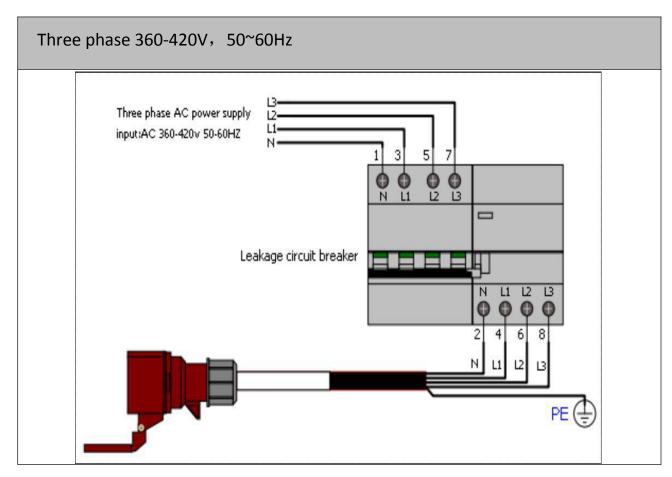
3 phase AC power supply, 380V, grounding voltage is less than 3V

The power cable specification must be no less than 4mm<sup>2</sup> GB

There must be a reliable grounding wire







### 2.Pre-installation

- 1. Prepare the working field under previous instruction.
- 2. Install distribution box under previous instruction, prepare a 15KVA voltage regulator.
- 3. Prepare 2 pcs of monkey wrench, 1 pcs of spirit level, 6L of coolant(pure water or anti-freeze fluid) for the LED lamp chiller.
- 4. Arrange a forklift for at least 8T(with extension arms) before the equipment arrives. If it needs to be unload from the container or hoisted to buildings, a crane will also be needed. Make sure the passage clear for the machine.







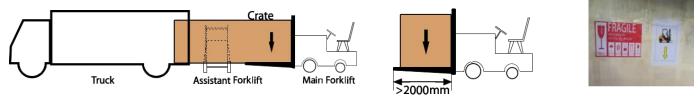


#### 5. Optional PC requirement

| Main board              | СРИ   | RAM | Hard disk | OS             |
|-------------------------|---|-----|-----------|----------------|
| PCI-E plug<br>supported | Intel corel5 above (Industrial pc)  | ≥8G | ≥500G     | Windows7 64bit |
| Ö                       | Handtop control software is not available in Windows8 and Windows10 system for the time being |     |           |                |

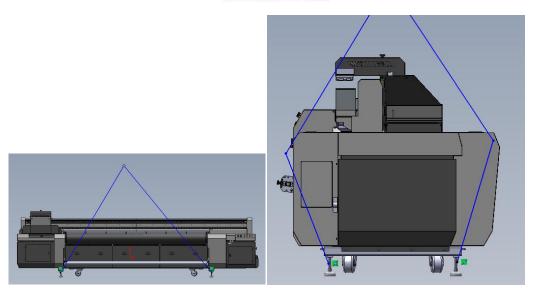
# 3. Transportation and unload

## 3.1Site transport



Another forklift would be needed if unload from a container or hoist onto building.





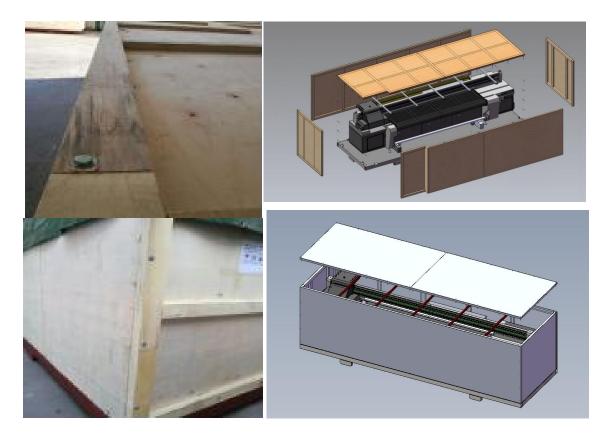
If lifting to upper floors needed, please mount the hoisting rope to the foot cups according to image 1 and 2, then proceed hoisting operation.

## Net weight: 2350kg Equipment size: 5530mm\*1320mm\*1325mm

| 0 | This printer is belong to heavy, high precision and expensive machine, it is highly recommended to hire professional carriers to perform loading and transport operations to avoid accidents.  |
|---|--|
| • | Must insert the forklift in the front side of the package box (Marked as FRONT)  |
| 0 | Please hoist the machine together with the package base when performing hoisting operations, this is to prevent the machine been distorted by outer force.   |
| Ϋ | The loading and transport of the machine would require forklift with more than 8T capacity. The distance between the arms should be at lease 2.0m, length of the arms should also be at least 2.0m (No less than the package box width). |



#### 3.2 Devanning process



- 1. First remove the screws on the top of box and the upper plate. then remove five red mounted bars. In order to avoid the damage from the bar against the machine, do remember hold the bar before unscrew the screws.
- 2. Remove the screw at the both side of the base plate to move the four sides' wooden plate.
- 3. Remove the machine fix screws and use forklift to lift the machine in the middle position. After check the machine foot are all working well, put the machine to the right place.

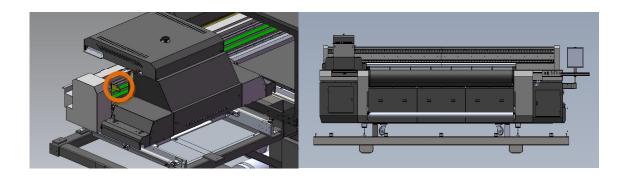
## 4. Installation

#### 4.1Check and confirmation

- 1. After the machine is located in the designated place, open the wooden package and first check the appearance of the machine and its internal circuit wiring status.
- 2. Confirm the spare parts list sent along with the machine and sign the packing list.



3. Remove the carriage locking parts on the right side of the beam, see the picture below

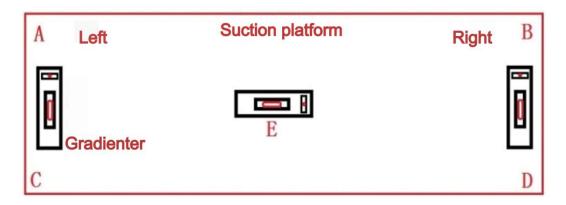


## 4.2 Equipment level adjustment

Tools: Level (Precision range 0.02mm/m), monkey wrench



When adjusting the level on the right/left side, the level should face the same direction.



#### Level position diagram

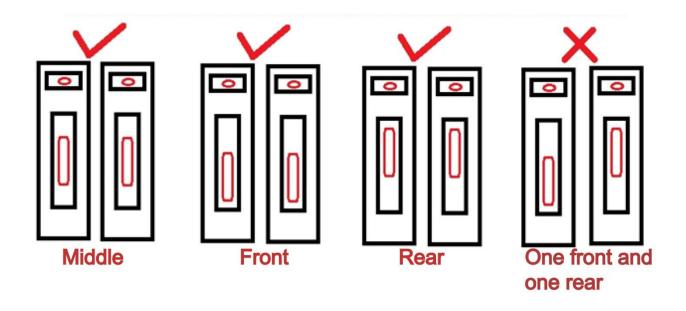
- 1. There are 6 main supporting foot cups on the machine body. First, raise up all the foot cups, and lower down the 4 foot cups in the corner of the frame, make sure they touch the ground. Jack up the foot cups until the yellow base leave the ground (5mm height would be enough)
- 2. Place the level on E position, check the height difference of left/right side



- 3. Place the level between position A and C, or between position B and D, check for the height for A,B,C,D points, then adjust the foot cup height according to the reference from step 2.
- 4. Adjust the 4 points to the same level with the assist of level, lock the foot cup screw to prevent loose
- 5. After the level adjustments, remove the yellow bases, lower down all the foot cups to the ground, lock the screws
- 6. Check the machine level again (Do not raise the foot cup too high, in case the machine shakes when running)



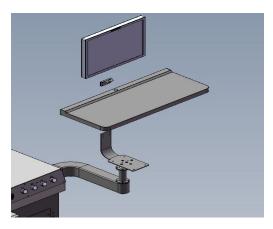
After adjusted the level, check for the error direction should be in the same direction (No more than 1 unit on the measure ruler) as below diagram shows.



## 4.3 PC component & External device installation

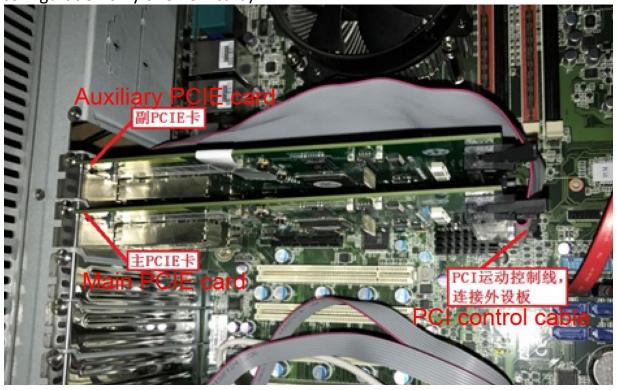
## 4.3.1 Install PC component





Install the display and PC according to the above picture and put the USB cable, PC start cable, display signal cable and power cable into the crate.

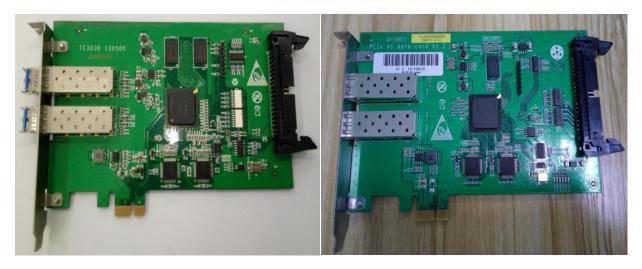
**4.3.2 Install PCIE cards** (Pictures below are for the 2X5 configuration, for 2x4 configuration only one PCIE card)



Install the PCIE card to the PC. Connect the movement control cable with the PCIE card and external device control board. Use the PC to connect the fiber cable for data transfer.

Difference of PCIE card between the 2x5 configuration and 2x4 configuration

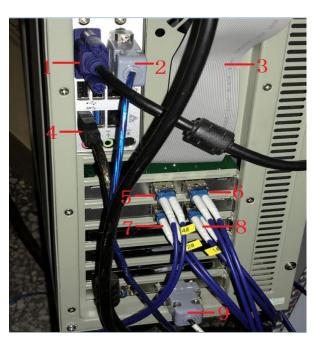




Kyocera 2x4 V1.1 PCIE card

Kyocera 2x5 V1.2 PCIE card

# **4.3.3 Connect the cables on PC** (Pictures below are for the 2X5 configuration, for 2x4 configuration only one PCIE card)



- 1. Display VGA Cable
- 2. X Axis Driver DP9 Cable
- 3. PCI Movement Control Cable
- 4. USB Communication Cable
- 5. Optical Fiber Cable No.4 (Connect to The Head Board No.4)
- 6. Optical Fiber Cable No.3 (Connect to The Head Board No.3)
- 7. Optical Fiber Cable No.2 (Connect to The Head Board No.2)
- 8. Optical Fiber Cable No.1 (Connect to The Head Board No.1)
- 9. Y Axis Driver DP9 Cable



#### 4.4 LED module installation

#### 4.4.1 LED lamp installation

- Install the LED lamp to the fixing plate at two side and connect the power cable, shutter control cable and anti-collision signal cable.
- The anti-collision module must be lower than jet plate with 0.5mm.

Put an acrylic on the platform and start the height detection function with 2mm setting. Lose the anti-collision plate screws and use the 1.5mm filler gauge to adjust the anti-collision plate height.

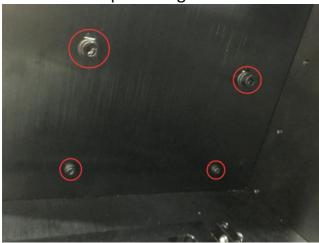




Plate screws

Adjust plate height

## 4.4.2 Chiller installation and setting









Connect the cooling circulation tube to the water hose. Then open the water-IN valve. Connect the power unit to 220V power and start the chiller working. Finally add the pure water(temp above  $10^{\circ}$ C) or anti-freezing water (temp under  $10^{\circ}$ C)



4.4.3 Setting of chiller



#### **OPERATION INSTRUCTION MANUAL**

**1.** The contents of the three digital displays are as follows:

D1 displays the real-time water temperature and displays the setting items when the status.

D2 displays the set value, displays the setting item value when setting the status, and displays the error code during the alarm.

D3 displays the monitoring temperature of the cooling system working condition, and displays the power value when pressing and holding the adjustable LED power.

**Default factory setting :** C0:15 C1:1.5 C2:60 C3:1 C4:20 C5:30 C6:3 C7:50



#### **2.** Button function introduction:

**AUTO:** (Smart mode) Entry method: Press once to enter the mode, press <u>AUTO key</u> (D1) again to display the room temperature, and automatically return to the display water temperature after 3 seconds.

**CONSTANT (constant temperature mode)** Entry method: same as smart mode entry method and function

**SET (Settings):** Entry method: Press <u>SET key</u> to enter the setting state, can adjust all the default parameters from C0 to C8, no operation button for more than 10 seconds or press SET button to exit the setting and save the parameters.

- + (minus and plus key): All parameters are modified by the plus or minus key.

(Up and down keys): Press the up and down keys to switch from C0 to C8 when entering the SET state; press the up and down keys to adjust the UV lamp power without entering the SET state (whether it is adjustable according to the actual situation of the UV manufacturer)

**QA**: phase A loss **QB**: phase B loss **QC**: phase C loss **QF**: phase sequence error **OK**: three phase normal

Press and hold the SET button for 4 seconds to reset all set values to the initial state.

#### 3. Control mode selection and working mode details

#### **CONSTANT (Constant temperature mode):** (factory default: 26 °C)

D2 displays the current set temperature value, directly press the plus or minus button to change the set value, real-time water temperature (D1) = set temperature (D2)  $\pm$  return difference value(C1). The setting range is 5°C - 40°C, the default is 30°C. In addition, the set temperature value cannot exceed the upper limit (C5), Lower limit (C4) temperature range.



#### **AUTO:** (Smart mode) (factory default: $-2^{\circ}$ C)

The D2 displays the difference value between the water temperature and the room temperature. Press the up and down keys to change the set value and set the temperature deviation range ( $-5^{\circ}\text{C}--+5^{\circ}\text{C}$ ), water temperature (D1) range = room temperature + (D2)  $\pm$  return difference value (C1). When the D1 range is not between C4-C5, the water temperature = upper limit (C5  $\pm$  return difference value (C1)), or lower limit (C4 + return difference value (C1)). For example, setting D2=1 $^{\circ}\text{C}$ , Room temperature = 25 $^{\circ}\text{C}$ , real-time water temperature D1 = 26 $^{\circ}\text{C}$   $\pm$  return difference value (C1), the actual water temperature D1 is controlled between 24.5 and 27.5 $^{\circ}\text{C}$ .

Regardless of the smart mode or the constant temperature mode, if the water temperature is lower than (lower limit C4-0.5 $^{\circ}$ C), the cooling is no longer performed, until the water temperature is higher than (lower limit C4+0.5 $^{\circ}$ C), then resume normal control.

If the water temperature is lower than (the set temperature of the heating rod C6-0.5°C), turn on the heating rod; When the water temperature is higher than (the set temperature of the heating rod C6+0.5°C), heating is stopped. (The heating rod can be equipped as needed, it is not equipped by default)

#### **4.** Setting item parameter codes introduction:

CO: Adjust the alarm difference (5.0-15.0 degrees): In the constant temperature mode, it indicates that if the difference between the target value and the set value exceeds the CO value, then the alarm signal is output; in the smart mode: if the difference between the water temperature and (the room temperature + the smart mode deviation value) is greater than the value of CO, then output an alarm signal.

C1: <u>return difference</u> value  $(0.1^{\circ}\text{C}-2.0^{\circ}\text{C})$ , default  $1.5^{\circ}\text{C}$ : In the smart mode and constant temperature mode, the up and down difference value that water temperature and the target temperature allowed. When this value is too small, the compressor starts frequently.

C2: Cold water machine system monitoring temperature alarm setting value  $(1^{\circ}C-100^{\circ}C)$ : This parameter is set by the factory to default to 60 degrees. Please contact the factory to modify this parameter.



C3: Water shortage alarm delay time (1S - 100S): Continue to work normally when the water shortage time is detected is less than this value.

C4: Lower limit temperature setting (1 $^{\circ}$ C-25 $^{\circ}$ C). If it is lower than this value, it will not be cooled; this value cannot be higher than the set temperature value of the constant temperature mode.

C5: Upper limit temperature setting (25°C-50°C), the water temperature is kept below the value of (C5+C1).

This value must be  $2^{\circ}$ C higher than the heating rod start temperature C6, and can not be lower than the set temperature value of the constant temperature mode, otherwise it cannot be adjusted.



C6: Heating rod start temperature (1 $^{\circ}$ C-20 $^{\circ}$ C): C6 is 2 degrees lower than C4, otherwise it cannot be adjusted.

C7: Maximum room temperature alarm function ( $42^{\circ}\text{C}-50^{\circ}\text{C}$ ): When the room temperature exceeds this C7, the alarm signal is output and the Cold water machine compressor stops working.

C8: Start mode, ON-machine starts when the machine is powered on, OFF-powers on and presses the power button to start.

#### General parameter description:

- $\times$  All temperature measurement display range: -20 °C ~ 99.9 °C.
- \*When the following conditions occur during the adjustment, the conflict will be caused, the adjustment will stop, and the buzzer will sound 3 alarms to indicate that the adjustment is invalid:
  - .The set temperature of the constant temperature mode exceeds the value of the upper limit temperature

C5;

.The set temperature of the constant temperature mode is lower than the value of the lower limit

#### temperature C4;

.The heating rod start temperature is higher than (lower limit temperature C4-2 $^{\circ}$ C);

When the above error conflict occurs and cannot be adjusted, you can return the conflicting items to modify them to resolve the conflict.

#### **5.** Fault protection function:



The meaning of the fault code is as follows:

E0: <u>2 PCB communication anomalies</u>. Generally <u>due to</u> the connection lines of the <u>2</u> boards are damaged or loose.

E1: Too high water temperature protection. Water temperature exceeds (target value + C0), too high protection fault output interrupt signal.

E2: Too low water temperature protection. Water temperature lower than (target value -C0), too low water temperature protection fault output interrupt signal.

E3: Water shortage protection. The pump does not pump water, the water pipe is blocked or the water flow is not smooth, and the water shortage protection is started, and the output interrupt signal.

E4: Refrigeration system fault. The cause of the fault is that the exhaust fan is broken, the condenser is blocked by dust, the air inlet is not smooth and etc., and output interrupt signal.

E5: High voltage protection. The high voltage switch is disconnected and start protection. Output interrupt signal. E6: Low voltage protection. The low voltage switch is disconnected and start protection. Output interrupt signal. E7: High room temperature protection. Output interrupt signal.

The protection or de-protection delay time is 2 seconds, and less than 2 seconds is regarded as interference and do not start protection.

If you do not need the E3/E5/E6, these 3 protection, you can directly short the sensor line.

After the fault protection is started, turn off the compressor and the heating rod, open the protection output, and open the solenoid valve. When the fault is removed, automatically resume working status. However, if it is E3 and E4 protection, only the protection relay will be activated, and other work will not be affected.

When the power is turned on, the difference between the water temperature and the target value may exceed the high and low temperature alarm limits. At this time, the alarm cannot be made, but at the same time detect temperature trends:

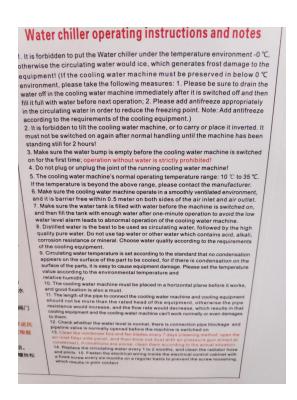


It is normal if it changes toward the target value and changes more than 0.3 degrees every 30 seconds.

If the change of continual 3 times \*30 seconds does not meet the requirements, then the alarm program detects if the temperature difference reaches the alarm value and then starts the alarm.

After an error alarm occurs, first troubleshoot, or modify the set parameters, then press the on/off key to restart, or power off and restart to continue working.

If the alarm is caused by the water temperature being too high or too low, the alarm can be temporarily canceled after adjusting the temperature or after switching the constant temperature/smart mode.



### 4.5 Main power installation

Check the voltage with multimeter before connect the cable. Land N are 220, L and PE are more than 3V. After confirm the power supply is OK, connect the power cable to the voltage stabilizer which need to connect the air switch after that. Make sure



the connection is correct and normal, switch on from ip to down. Main power locker should open to the up before turn on the main power and connect to the electricity. Finally start the PC and machine.

# **5.Software Installation 5.1Topjet Installation**

1 Select the driver version accordingly

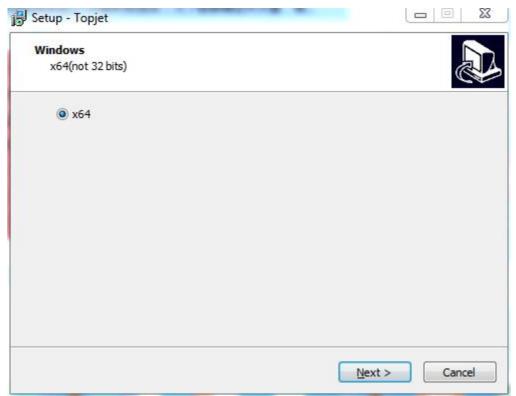


2 Double click the driver, choose language

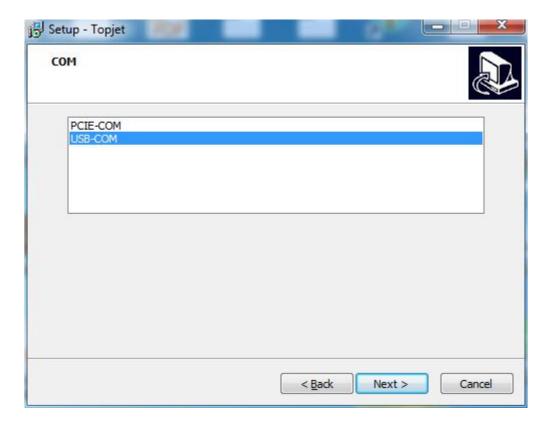


3 Select X64, only available for WIN 7 64bit OS



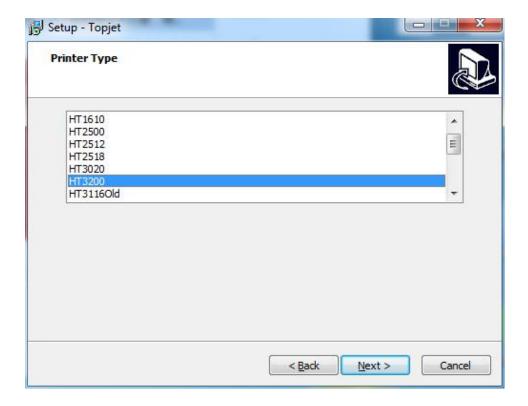


4 Select the communication port

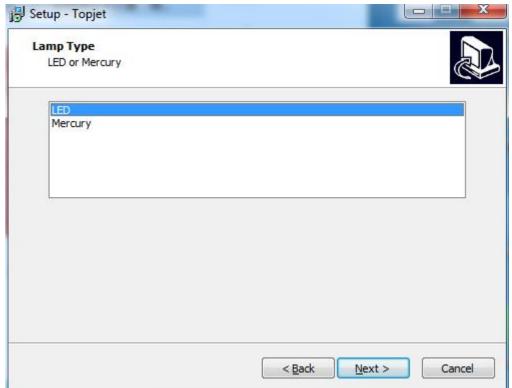


Select the printer model





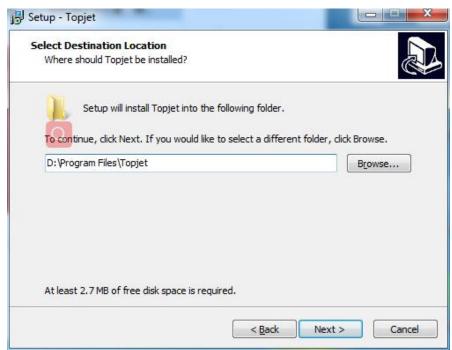
6 Select lamp type



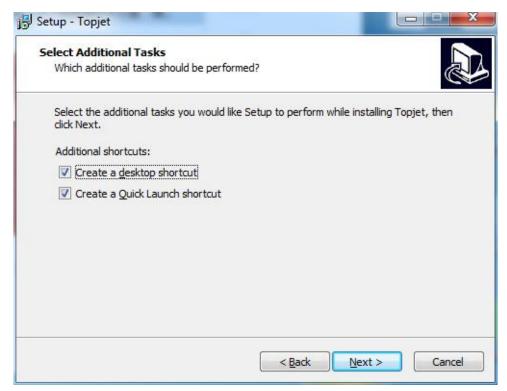
7 Browse a path for TopJet.



It's recommended to not choose system disk as installation folder. For example, "E:\". Thus, the package will generate a folder named "E:\TopJet" automatically.

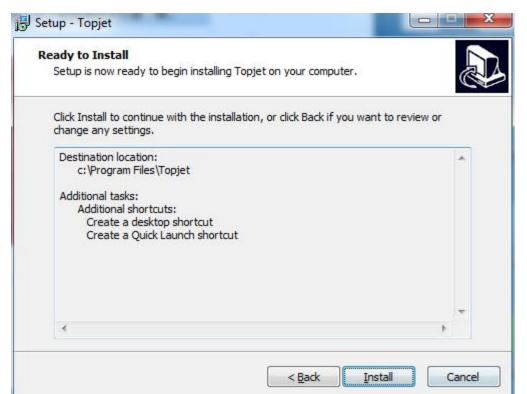


8 Select additional task

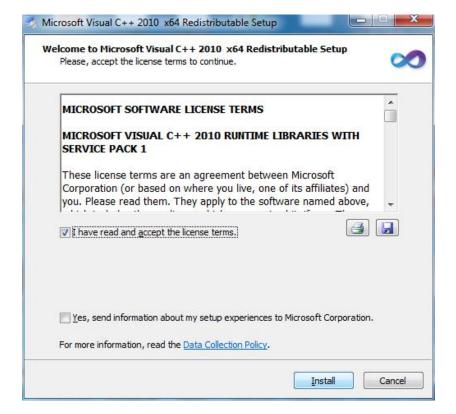


9 Install





10 Install



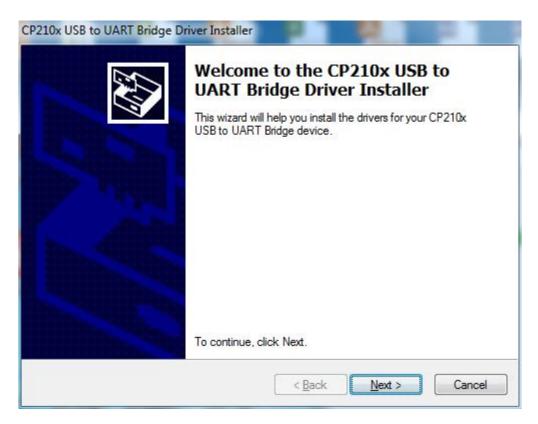
11 Click finish to continue

11





## 12 Install the driver for PCIE card





### Accept and click next



## 14 Continue



15

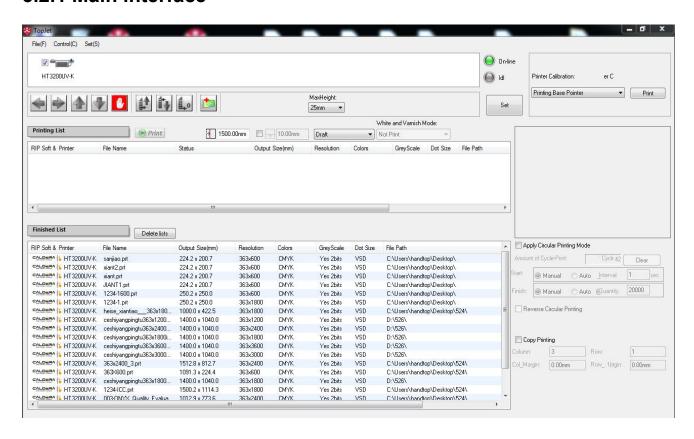


Finish. Normally we do not have to reboot computer after installation.





#### 5.2.1 Main interface

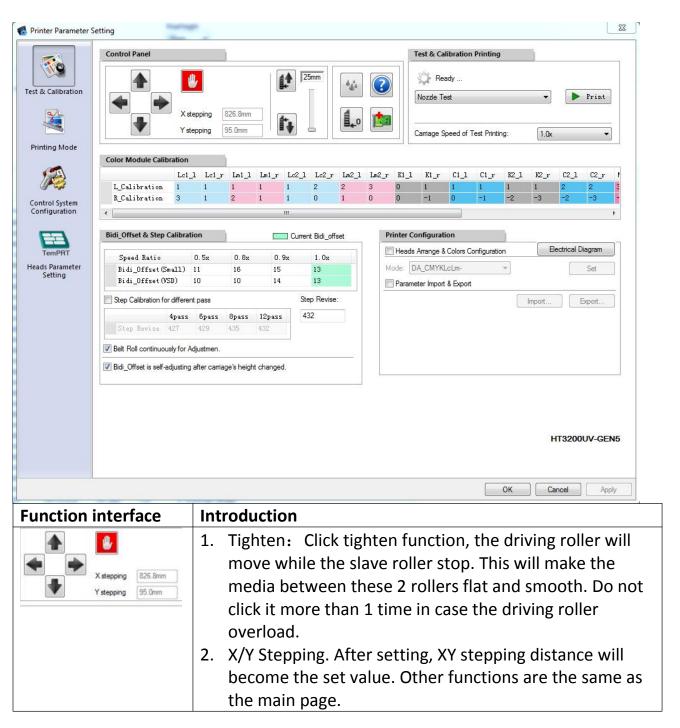


| Function interface      | Introduction  |  |  |
|-------------------------|---|--|--|
|                         | Controlling the carriage right/left motion, Y direction             |  |  |
|                         | front/rare motion   |  |  |
|                         | Stop button   |  |  |
| 1 1 10                  | Up and down carriage motion, zero adjust for height sensor          |  |  |
| rta .                   | Equipment diagnose, the machine will automatically run the          |  |  |
|                         | diagnose by a click   |  |  |
| Printing List           | List for awaiting printing files                                    |  |  |
| Finished List           | Finished printing files   |  |  |
| Print                   | Print button, it will be in grey color if no printing file selected |  |  |
| 1000.00mm 200.00mm      | Margin and header settings  |  |  |
| White and Varnish Mode: | List for white and varnish printing modes, this model doesn't       |  |  |
| Not Print ▼             | support varnish function  |  |  |
| Set                     | Advance settings  |  |  |

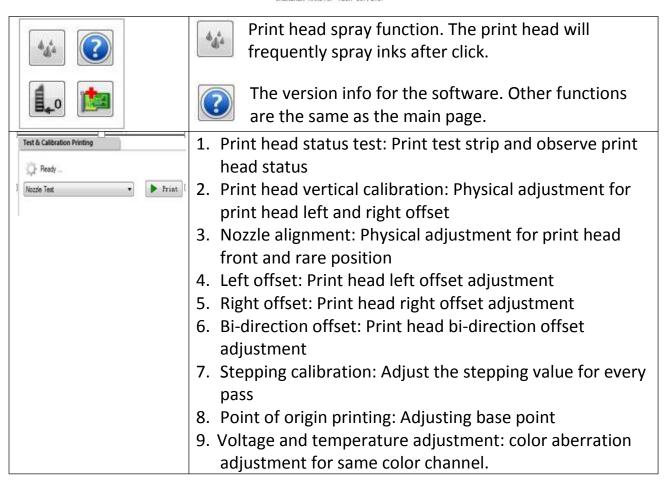


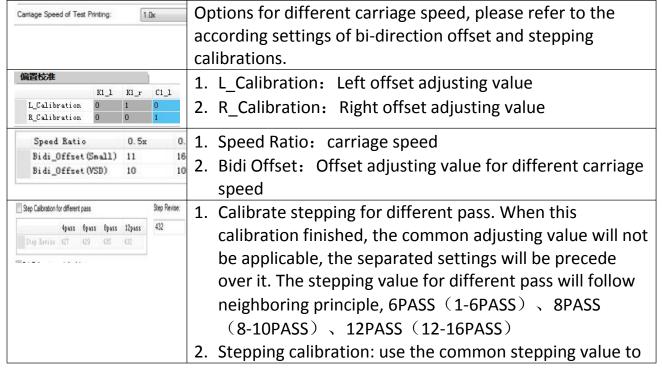
| Printer Calibration:  Nozzle Test ▼ Print   | Calibration printing list   |  |
|---|---|--|
| Apply Circular Printing Mode  | Circular printing mode including auto and manual options, do not select it while copy printing is selected. |  |
| Copy printing function, can't be selected together with circ printing at the same time. |   |  |

### 5.2.2 Test and calibration interface







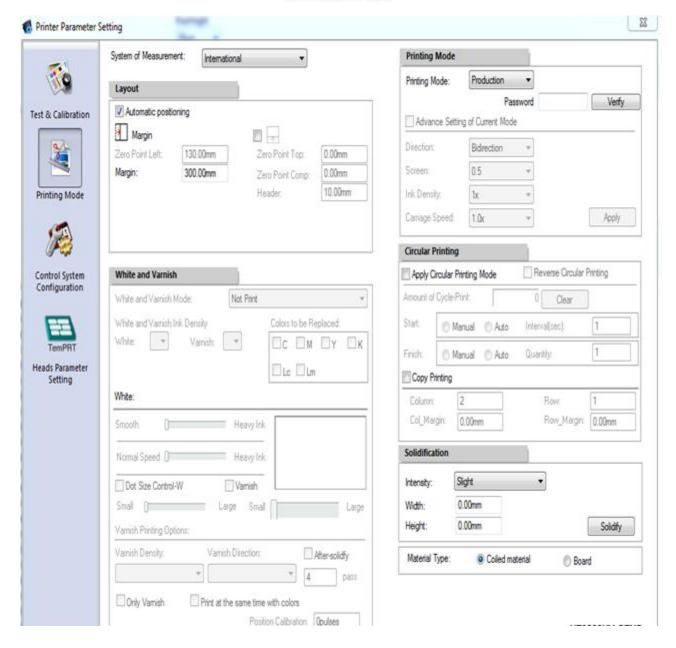




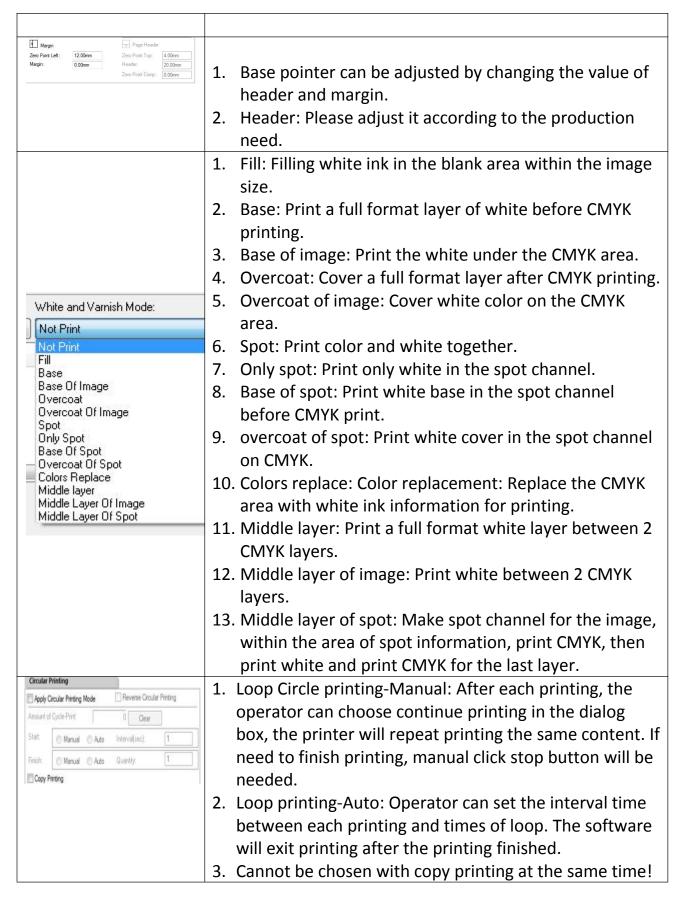
|   |    | adjust the stepping   |  |
|---|----|---|--|
| Belt Roll continuously for Adjustmen.                           | 1  | This model does not support "Continuous stepping to   |  |
| ☑ Bid_Offset is self-adjusting after carriage's height changed. |    | adjust the belt"  |  |
|   | 2. | During the printing, the carriage will automatically adjust if the carriage height changes. The bi-direction offset will automatically adjust its self if the carriage height changes for adapting the media thickness in the printing process. If manual adjustment needed for bi-direction offset during printing, close this function first. |  |
| Printer Configuration   | 1. | Print head array  |  |
| Heads Arrange & Colors Configuration   Bectrical Diagram        |    | The import and export of printing settings: Export the readings for the settings as XML file as a back up for all   |  |
| Import Export   |    | the settings. Restart the program after every change  |  |

## 5.2.3Setting interface for printing mode

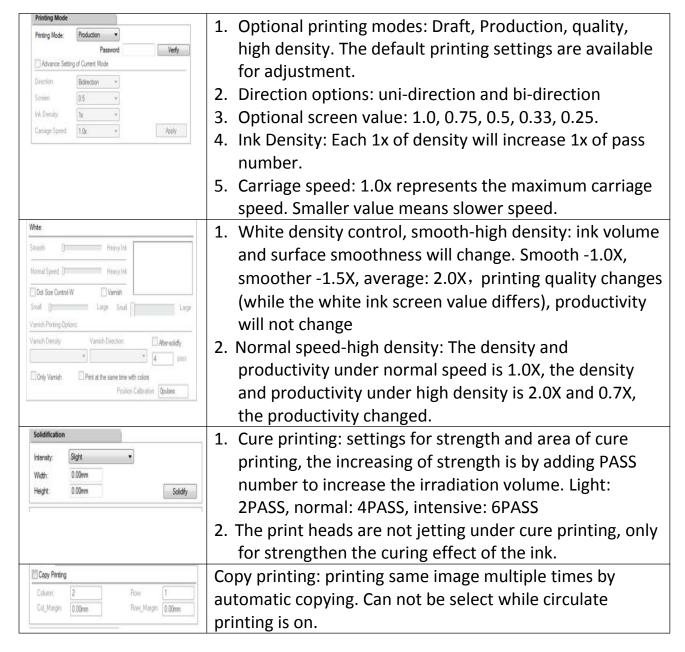






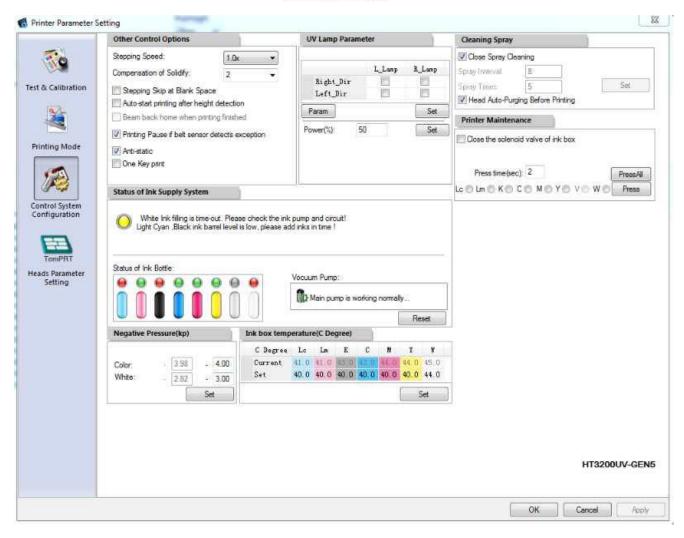






### 5.2.4Control system parameter interface



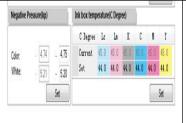


| 1. Spray setting: An intermittent jetting motion when the print heads are under nonworking state. This function is           |
|--|
|  |
|  |
| to prevent the ink block the nozzle under long time of   |
| settling. Press the set button to confirm after the  |
| settings been altered.   |
| 2. Select the auto spray before printing option, the printer will perform spray before each printing task as default motion. |
|  |

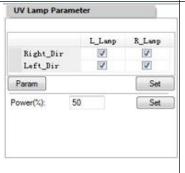




- 1. Motion control option: Settings for printer motion control.
- 2. Stepping speed and curing compensation: This function is to compensate the curing pass and stepping speed after the printing finished. Stepping speed options include 1.0x and 1.3x, curing compensation include 2/4/6pass.
- 3. Stepping Skip at Blank Space: After selected, the printer will skip the blank area of image while printing the job.
- 4. Auto printing after height detect finish: after selected, the printer will automatically start printing after the height detect is over.
- 5. Static suppress printing: The switch for anti-static bar, selected means the anti-static is on.
- 6. One key print: After selected, the printer can continue to print by pressing the "one key printing" button or double click "print".
- 7. The option in grey color means cannot be selected, the printer doesn't support that function.

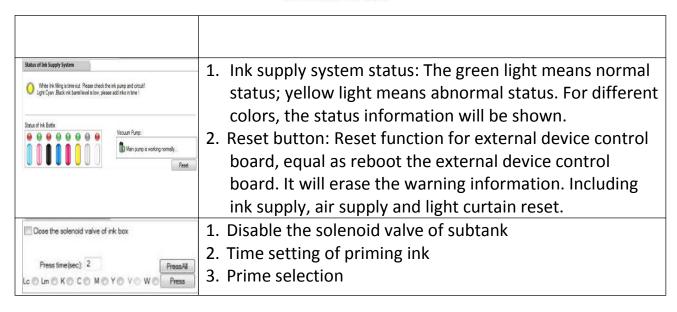


- 1. Negative pressure settings: Including color negative pressure and white negative pressure. Grey colored data represents the detected negative pressure, black colored date is the set negative pressure.
- 2. Negative pressure setting range: 0.5~10Kpa.
- 3. Default negative pressure: -6.0Kpa.
- 4. Ink tank temperature settings: This is the heating temperature setting for sub-tank, it is divided as the real time temperature and the setting value, default setting is  $40^{\circ}\text{C}$ .

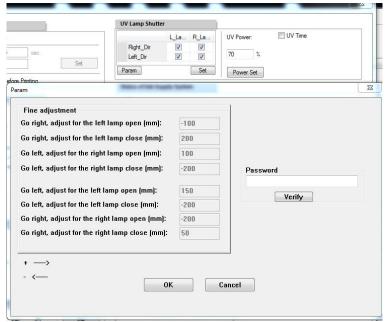


- 1. UV lamp shutter working mode: Switches for controlling the L&R movement for the L&R lamp. Only when the corresponded switch been selected, the shutter would open accordingly.
- Parameter settings: Modify the on/off position of the LED lamp within the printing area. (For adjust instruction please refer to (4-1) Control parameter interface-Settings for LED lamp on/off position control).
- 3. UV power: Energy control for LED lamp, adjusting arrange: 0%~100%.





### 5.2.5 GUI control---LED ON/OFF setting

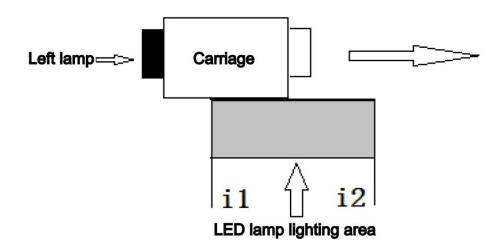


The adjusting password of the shutter (LED light source) opening and closing position is **ua13**. After input, click verification to enable the fine tuning setting function. The 8 parameters on the left are fine-tuning parameters in millimeters. The parameters are described in detail as follows:

Left light on position adjustment (mm) of the left light when the car moves to the right and left light off position adjustment when the car moves to the right (mm): According to the figure below, the top right arrow indicates that the car is moving to the right, and the black solid rectangle on the left side of the car indicates the left curing light. The vertical line i1 represents the position where the UV curing lamp is turned on, while the vertical line i2 represents the position where the UV curing lamp



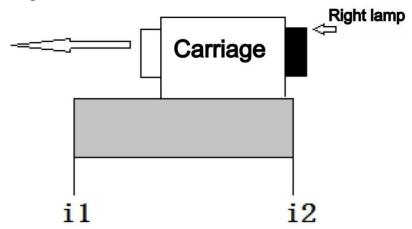
is turned off. The grey area between i1 and i2 is the radiation area of the curing lamp on the left of the car. If the irradiation area is found not to coincide with the image, two parameters, "left light on position adjustment (mm) when the car moves to the right" and "left light on position adjustment (mm) when the car moves to the right" need to be adjusted. "When the car moves to the right, the position adjustment of the left light on (mm)" adjusts the position of vertical line i1. "when the car moves to the right, the position adjustment of the left light on (mm)" adjusts the position of vertical line i2. Enter a positive number, indicating the position moves to the right; Enter a negative number to indicate a move to the left. Note that the value entered represents the amount of movement, for example 10, which represents a 10 mm movement to the right.



The position adjustment of the right light on when the car moves left (mm) and the position adjustment of the right light off when the car moves left (mm): According to the figure below, the upper left arrow indicates that the car is moving to the left, and the black solid rectangle on the right side of the car indicates the right curing lamp. The vertical line i2 represents the position where the UV curing lamp is turned on, while the vertical line i1 represents the position where the UV curing lamp is turned off. The grey area between i1 and i2 is the radiation area of the curing lamp on the right of the car. If it is found that the irradiation area does not coincide with the image, two parameters, "right light on position adjustment (mm) when the car moves left" and "right light on position adjustment when the car moves left (mm)" need to be adjusted."When the car moves left, the position adjustment of the right lamp on (mm)" adjusts the position of vertical line i2. "when the car moves left, the position adjustment of the right lamp on (mm) adjusts the position of vertical line i1. Enter a positive number, indicating the position moves to the right; Enter a negative number to indicate a move to the left. Note that the value entered Represents the amount of movement, for example, 10, which represents a 10 mm



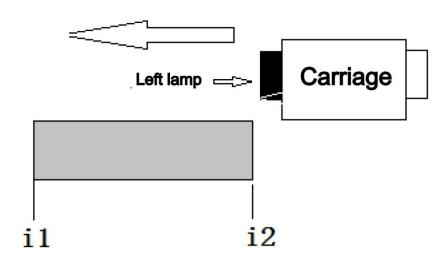
movement to the right.



Left light on position adjustment (mm) of left light when car moves left and left light off position adjustment of left light when car moves left (mm):

According to the figure below, the upper left arrow indicates that the car is moving to the left, and the black solid rectangle on the left side of the car indicates the left curing light .The vertical line i2 represents the position where the UV curing lamp is turned on, while the vertical line i1 represents the position where the UV curing lamp is turned off. The grey area between i2 and i1 is the radiation area of the curing lamp on the left of the car. If the irradiation area is found not to coincide with the image, two parameters, "left light on position adjustment (mm) when the car moves left" and "left light on position adjustment (mm) when the car moves left", need to be adjusted. "When the car moves left, the position adjustment of the left light on (mm)" adjusts the position of vertical line i2. "when the car moves left, the position adjustment of the left light on (mm) adjusts the position of vertical line i1. Enter a positive number, indicating the position moves to the right; Enter a negative number to indicate a move to the left. Note that the value entered represents the amount of movement, for example, 10, which represents a 10 mm movement to the right.

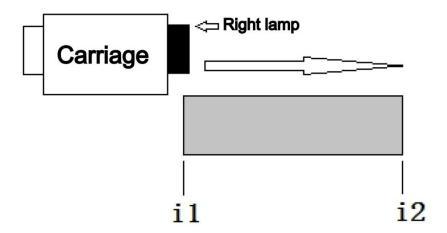




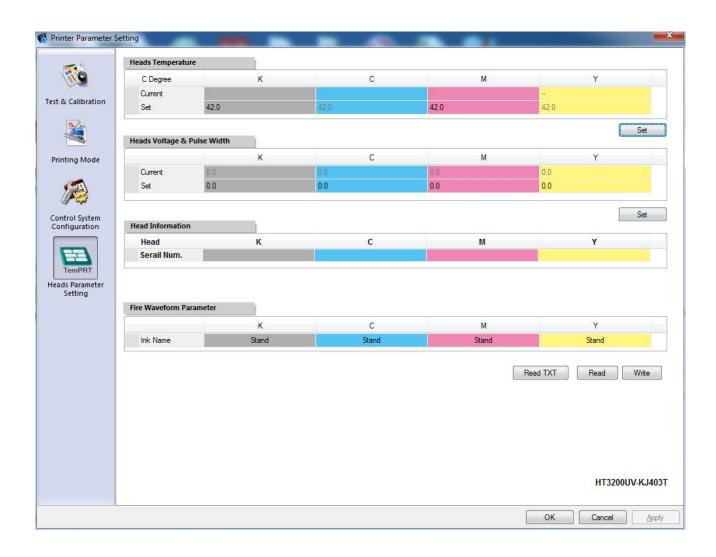
The position adjustment of the right light on when the car moves to the right (mm) and the position adjustment of the right light off when the car moves to the right (mm):

According to the figure below, the large right arrow above indicates that the car is moving to the right, and the solid black rectangle on the right of the car indicates the right curing lamp. The vertical line i1 represents the position where the UV curing lamp is turned on, while the vertical line i2 represents the position where the UV curing lamp is turned off. The grey area between i1 and i2 is the radiation area of the curing lamp on the right of the car. If it is found that the irradiation area does not coincide with the image, two parameters, "right light on position adjustment (mm) when the car moves to the right" and "right light on position adjustment (mm) when the car moves to the right", need to be adjusted. "When the car moves to the right, the position adjustment of the right lamp on (mm)" adjusts the position of vertical line i1. "when the car moves to the right, the position adjustment of the right lamp on (mm)" adjusts the position of vertical line i2. Enter a positive number, indicating the position moves to the right; Enter a negative number to indicate a move to the left. Note that the value entered represents the amount of movement, for example, 10, which represents a 10 mm movement to the right.





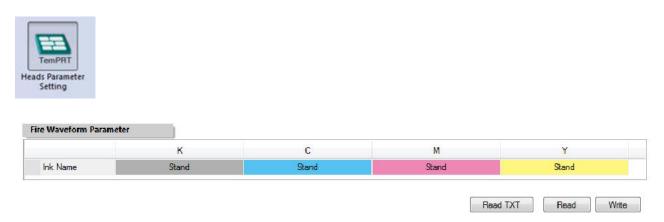
## 5.2.6 Heads parameter Setting



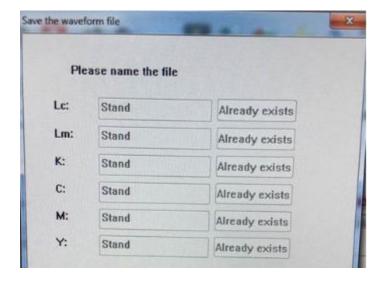


### 5.3 Kyocera waveform writing

After finishing the installation of heads, enter "head parameter setting"

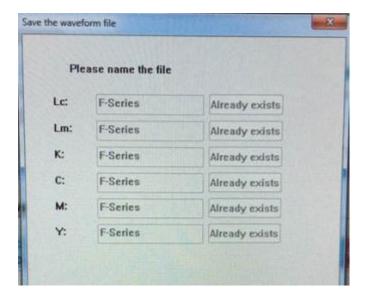


First select "stand" waveform, click "write", wait for 1min, then click "read" to check if the waveform is written successfully. (If not, please do it again.)



Then select the waveform you want(e.g. F-Series), click "write", wait for 1min, then click "read" to check if the waveform is written successfully. (If not, please do it again.)





### 6. Printhead installation and calibration

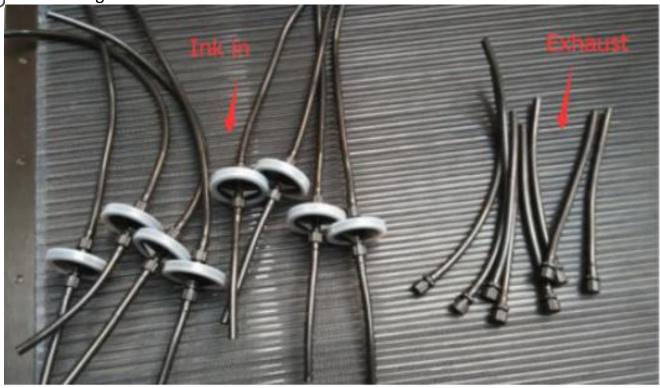
## 6.1 Print head installation process

- This operation should be performed by professionally trained personnel to avoid accidental injury or device damage.
- The ribbon cable must be connected in the event of a power outage, and the pin of the ribbon cable must not be stained with ink or flush.
- 1 Find out the necessary accessories and confirm, The pictures are as follow:





2 Assembling head inlet and outlet ink tube.



Check the filter and the inlet tube, make sure the lower tube is thicker than upper tube, then connect the big connector. Also connect the outlet tube with the small connectors.



The side marked with inlet connects to the sub-tank, and the other side connects to the printhead.





Finish assembly of tube, as shown in picture below. (Left is the outlet tube, right is the inlet tube)





### Clean all tubes with flush

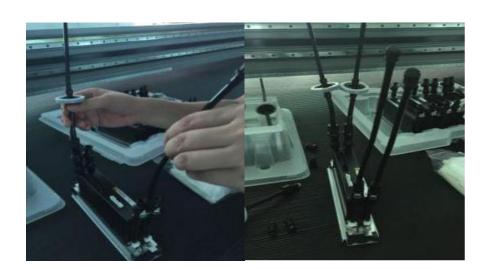
5



## 6 Connect the tubes with the heads

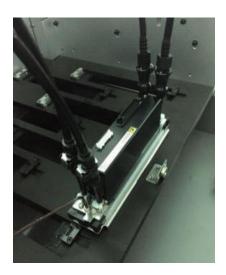


### 7 As shown in pictures below

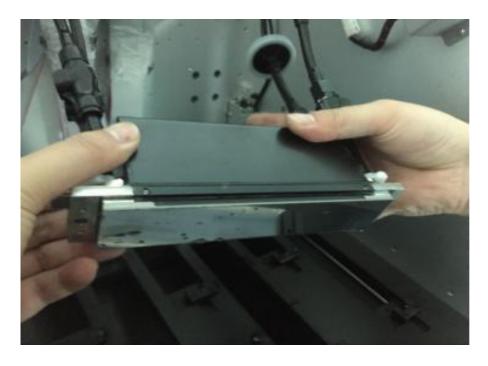




 $iggl[ oldsymbol{8} iggr]$  Remove the screws on the plate. (one is at the back side, one is at the front side)



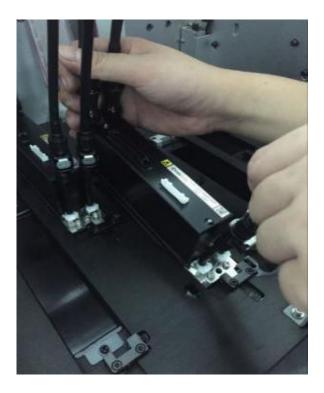
## 9 Remove the protective film



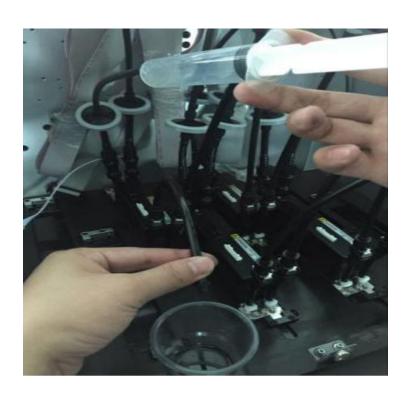


## Put the head to the right position



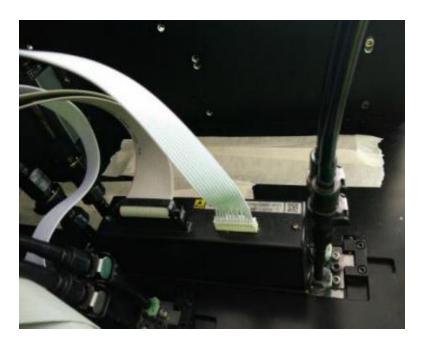


## 11 Discharge the protective fluid of the head

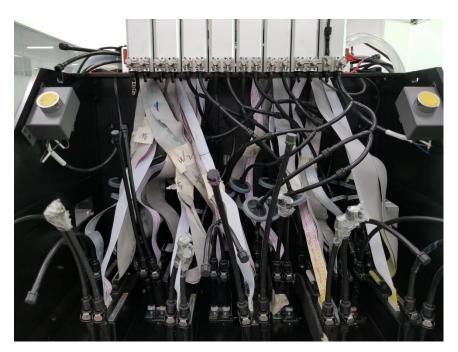




Connect the head cables, grey is data cable, the white is power cable.

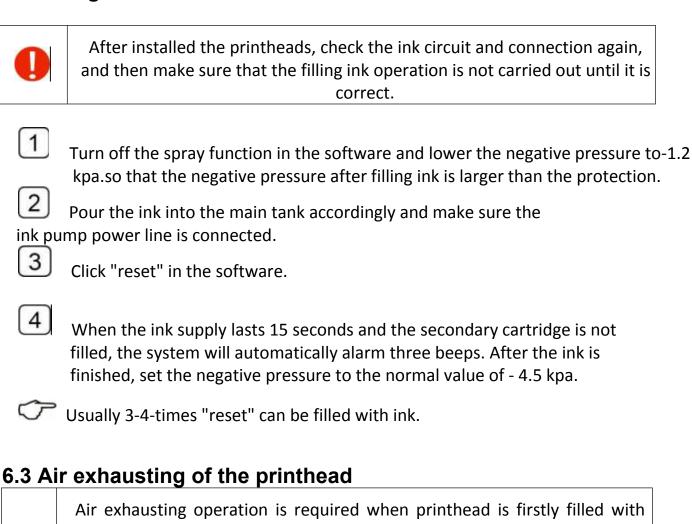


## 13 After finish all assembly, as shown in picture below





### 6.2 Filling ink





Air exhausting operation is required when printhead is firstly filled with ink, in order to eliminate the air bubbles inside the printhead, so that the ink can be supplied continuously while the printhead is jetting, thus avoiding the missing nozzle during the printing.

This method also can be used in the subsequent nozzle maintenance operation.

| 1           | Turn off spray cleaning function.   |
|-------------|---|
| 2<br>exhaus | Lower the negative pressure to -1.5 kpa, and open the printhead that needs t, press the corresponding pressure switch at the same time. |



Loosen the cap of the air exhaust tube of the printhead, and press the ink prime button till you see a constant ink stream comes out of the tube. Then seal the tube with the cap. Execute the exhaust on each printhead as the operations described above.



The operation must not exceed 3 seconds so as to avoid the generation of bubbles. If the system alert occurs, click the "reset" and continue the exhausting operation when the alert ceases.

- When finishes exhaust operation, adjust the pressure to normal value(-4.5~5.0Kpa) and turn on all the valve, press the prime button till you see the ink comes out of the nozzles of each printhead.
- Use the wiper to wipe all the printheads.
- $\stackrel{\textstyle 6}{\textstyle \smile}$  Print a "nozzle test" and check the status of the nozzles.

### 6.4 Parameter setting before calibration

- Reference negative pressure for color is -5kpa, reference negative pressure for white is -5.2kpa.
- 2 Set temperature, voltage for printheads, the temperature of subtank.

## 6.5 Instructions for the Calibration 6.5.1 Heads vertical

- 1 Run Topjet, Click "Set".
- 2 Choose "heads vertical" in the drop-down menu and print.
- Observe the calibration print through a magnifying glass and see if the upper and lower parts overlap.



- According to the testing picture, adjust the vertical alignment screw and repeat step 3.
- Repeat step2/3/4 till the calibration of heads vertical is ok.

| How to observe the testing picture of heads vertical?   |   |  |  |  |
|---|---|--|--|--|
| Testing picture of  | Testing picture of heads  |  |  |  |
| heads vertical (Overlapped)   | vertical (not overlapped)   |  |  |  |
| Clockwise Anticlockwise   |   |  |  |  |
| Exclamation point position, two groups of lines completely overlap, Heads vertical calibration is OK. | Reclosing in the "clockwise" direction, adjust the vertical alignment screw to clockwise. |  |  |  |

### How to adjust the Vertical alignment screw?

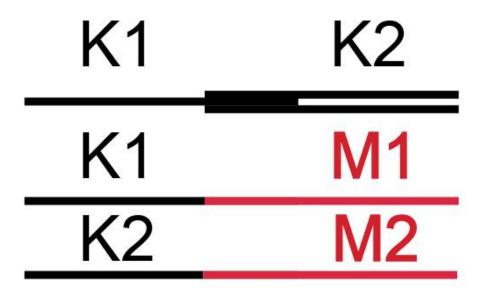
Release the fixing screws of printheads, adjust vertical alignment screws according to the testing picture, Fasten the fixing screws of printheads when they are overlapped

### 5.2 Nozzle alignment



- Choose "Nozzle alignment" in the drop-down menu and print.

  Observe the calibration print through a magnifying glass and see if the left and right parts overlap.
- Adjust the horizontal alignment fixing screw according to the calibration printing coincidence.
- Repeat step 1 / 2 / 3 till nozzle alignment is ok, see the picture below.





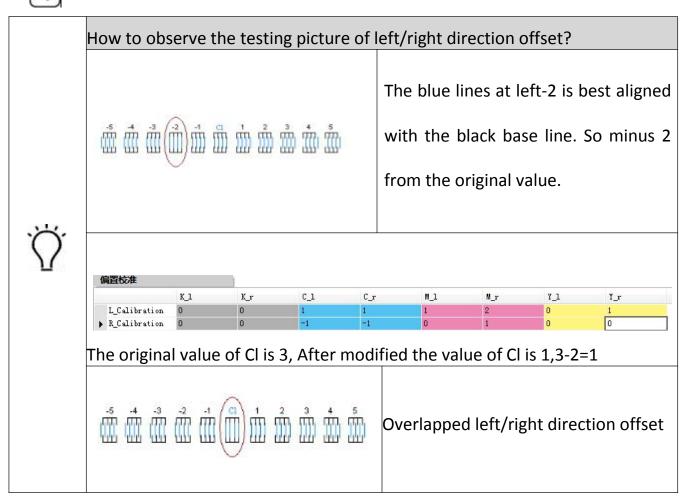
### 6.5.3 Left/right direction offset



Left/right direction offset indicates the calibration parameters of the nozzle jetting from left to right and from right to left.

- 1 Select "Left direction offset" in the drop-down menu and print.
- Observe the calibration print through a magnifying glass

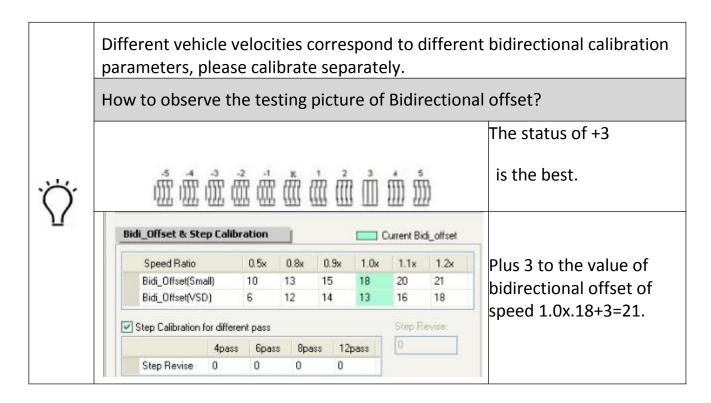
  Write down the corresponding parameters that have been aligned.
- 3 Modify the parameter of left direction offset according to step 2.
- Repeat step 1 / 2 / 3 till left direction offset is ok.



#### 6.5.4 Bidirectional offset



- 1 Select "Bidirectional offset" in the drop-down menu and print.
- Observe the calibration print through a magnifying glass and write down the aligned parameters.
- Repeat step 1 / 2 / 3 at corresponding speed for modifying bidirectional offset till Bidirectional offset is ok.

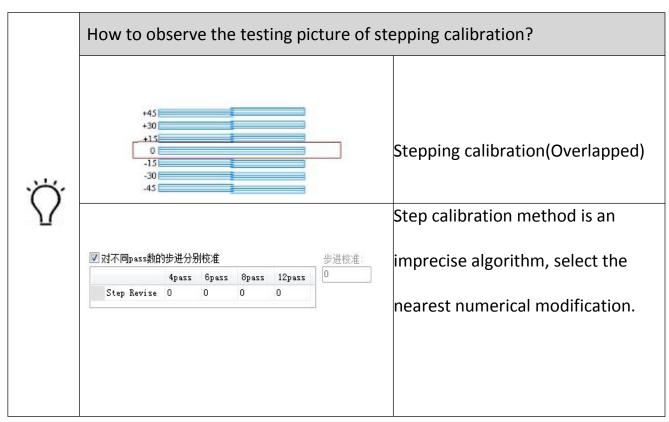


#### 6.5.5 Stepping calibration

- Select "Stepping calibration" in the drop-down menu and print.
- Observe the calibration print through a magnifying glass and write down the aligned parameters.
  - Modify the step bias parameter in the corresponding position.

Repeat step1/2/3 till the stepping calibration is ok.

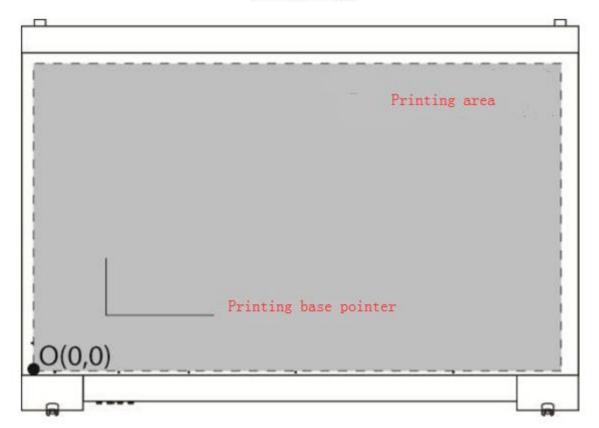




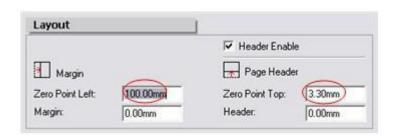
#### 6.5.6Calibration of printing base pointer

- Select "Printing base pointer" in the drop-down menu and print.
- Measure and calculate the difference between the actual value and the expected value.





3 Modify the page header base point based on the margin.





#### 6.6 Calibration confirmation



This test picture checks the status after calibration.

# 7. White printing Mode

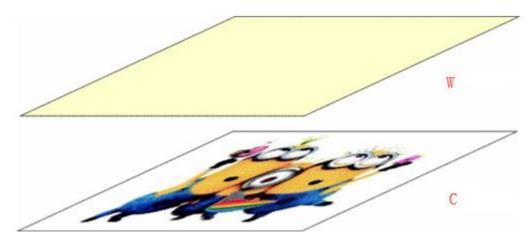
# 7.1 Not print

Only color layer is printed.

#### 7.2 Overcoat

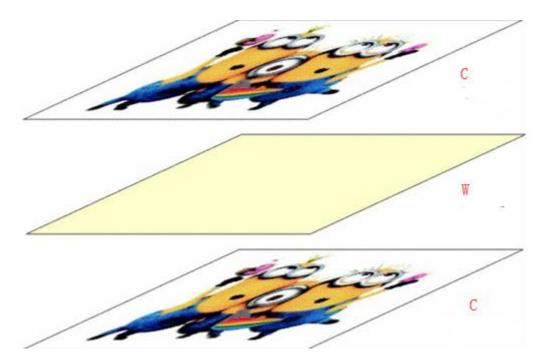
Within the image frame, above the color layer, print solid density white.





# 7.3Middle layer

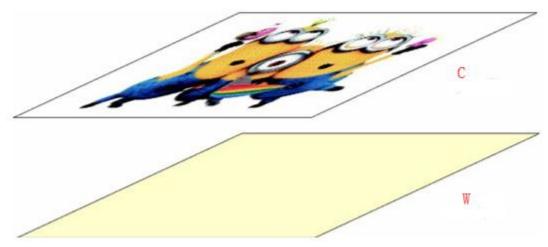
Within the image frame, in between the top and bottom color layers, print solid density white.



#### **7.4 Base**

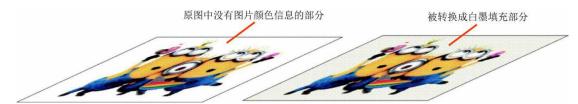
Within the image frame, under the color layer, print solid density white.





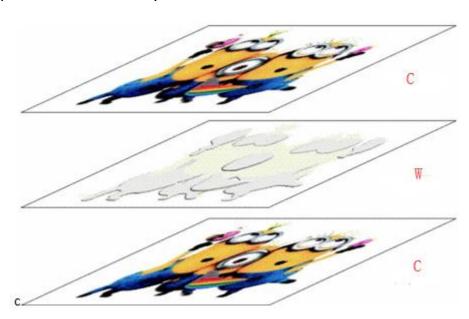
#### **7.5 Fill**

Within the image frame, in the empty(no color data) area, print solid density white.



# 7.6 Middle layer of image

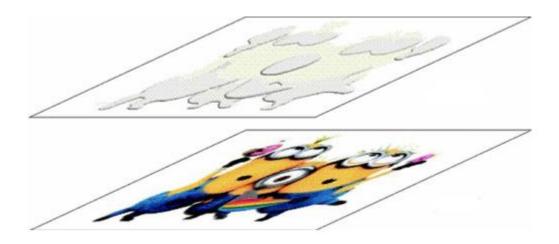
In the area where there is color data, in between the top and bottom color layers, print variable density white based on the color data.





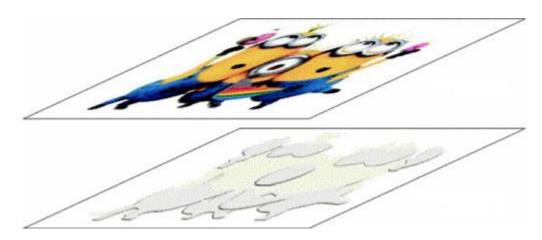
#### 7.7Overcoat of image

In the area where there is color data, above the color layer, print variable density white based on the color data.



#### 7.8 Base of image

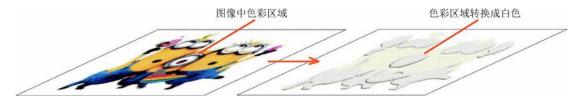
In the area where there is color data, under the color layers, print variable density white based on the color data.



### 7.9 Color replacement

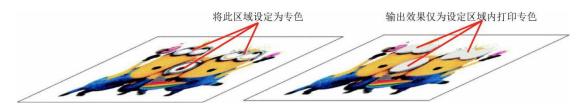
In the area where there is color data, print only variable density white based on the color data, color is not printed.





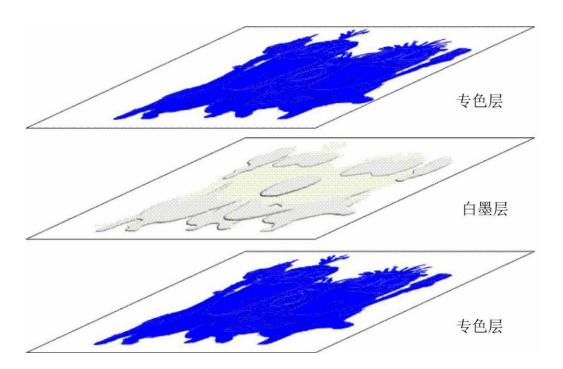
### 7.10 Spot

In the area defined as spot, print white based on the spot channel density data.



#### 7.11Middle layer of spot

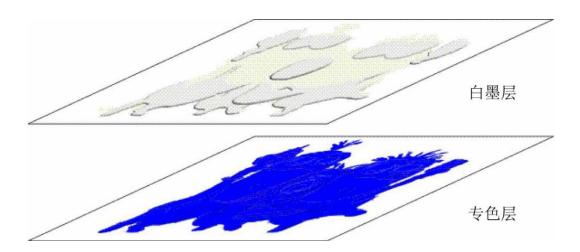
In the area defined as spot, in between the top and bottom color layers, print white based on the spot channel density data.





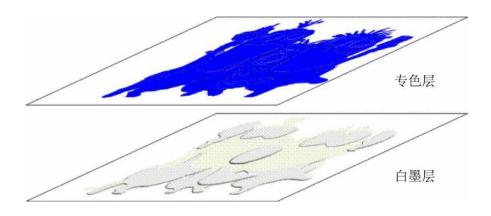
#### 7.12Overcoat of spot

In the area defined as spot, above the color layer, print white based on the spot channel density data.



#### 7.13Base of spot

In the area defined as spot, under the color layer, print white based on the spot channel density data.





#### Operation instruction

# 1.Machine turn-on

| 0 |    | Pay attention to the safty instruction in chapter 6; First operation must under professional techinical engineers' gui | idence.  |
|---|----|--|----------|
| 0 |    | Use E-stop when meeting urgent issue, to protect the machine.  |          |
| 1 | Co | onnect the main power cable  |          |
| 2 | Tu | irn on the main air switch   |          |
| 4 | St | art the PC   |          |
| 5 | Tu | ırn off the E-stop and turn on the start button for machine self c   | hecking. |
| 6 | Ch | neck the negative pressure setting on the GUI  |          |
| 7 | Lo | ading material and turn on the suction   |          |
| 8 | Tu | ırn on the LED lamp  |          |
|   |    | Button position refer to the machine drawing pictures  |          |
|   | Û  |  |          |
|   |    | Refer the alarm system information   |          |
|   |    | ý l  |          |



# 2.Machine turn-off

- 1 Testing strip printing
- Fan and LED lamp OFF
- Check the negative pressure and sprary function
- 4 PC OFF
- Machine cleaning



Maintenance instruction

# 1. Periodic maintenance



To ensure the good condition of the equipment, users need to follow below instructions for regular cleaning and maintenance of the equipment.

|                   | Clean the machine body                           |
|-------------------|--|
|                   | Empty the waste ink                              |
| Daily maintenance | Clean printhead mounting plate                   |
|                   | Check the negative pressure system               |
|                   | Check the nozzle test (print head status)        |
|                   | Clean the chain and organize the internal wiring |
| Weekly            | Clean the fan and cabinet                        |
| maintenance       | Clean waste ink tank                             |
|                   | Calibrate  |



|                     | Add lubricating grease to motion parts  |
|---------------------|---|
| Monthly maintenance | Check ink tube and air tube connections |
| mameenance          | Replace the air pump                    |
|                     |   |
| Seasonal            | Replace the ink pump filter             |
| maintenance         | Replace ink pump and fiber cable        |
|                     |   |
| Annual              | Replace the printhead filter            |
| maintenance         | Replace the ink tube in the chain       |

# 2. Motion component maintenance

| The mechanical motion parts are lubricated with lithium base grease and lubricated once a month |   |  |
|---|---|--|
| Mechanical motion unit  | X axis guide rail  Gears on feeding and take up torque motors  Rectify guide rail and leading screw |  |
| , Ö.  | Use a lever type grease gun to grease the slider from lubricating nipple on the slider              |  |
| $\triangle$   | Do not use non-lithium base grease, keep the grease clean from damaging the guide rail and slider.  |  |



#### 3. Precision components maintenance

| Must use absolute alcohol and clean cloth for the cleansing of the precision components. |                                   |  |
|--|-----------------------------------|--|
|  | Raster strip                      |  |
| Precision components   | Photoelectric switch              |  |
|  | Carriage height sensor components |  |

#### 4. Printhead maintenance

#### 4.1 Daily maintenance of printhead

Print the nozzle test every on and off duty, check for nozzle status see if any blockage

If there are nozzles blocking, dispose immediately.

When printing images with single color, it is recommended to add right observation strip to ensure all the other colors are jetting. This is to prevent blocking from long time of print head resting.



Be sure to check the flatness of the material after putting it on the platform, prevent nozzle scratching.

- Clean the dust and debris on the printing platform and carriage base every day
  - Must remove dust and static charge from the substrates.



# 5. Commonly used parts replacement instructions

# 5.1 Replace the ink pump

When the machine is alarming 3 beeps, check the ink pumps



This is not the only possibility, see the alarm system

Unplug the ink pump power housing and loose the fixing screw;





Replace with new ink pump;



Cut off the ink pipe connected to the old pump;



| (  | Connect the ink pipe to the new pump. Pay attention to the flow direction, fix |  |  |  |
|----|--|--|--|--|
| th | the screw, and   |  |  |  |
| CC | nnect th   | e power housing.   |  |  |
|    | $\overleftarrow{\bigcirc}$   | It is normal to hear 3 beeps during the procedure.                               |  |  |
|    |  | Click "Reset" in the software to finish.   |  |  |
| 5  | 2 Add  | ink  |  |  |
|    | Ϋ  | If you hear 6 beeps, check the main tank see if it is running out of ink.        |  |  |
|    | Ö  | Note that the ink drawing tube for the main tank must be inserted to the bottom. |  |  |
| Ċ  | 1 Pre  | epare the new ink, open the cover and keep it handy;                             |  |  |
|    | 2 Op   | en the lid of the main ink and carefully pour the ink into it;                   |  |  |
| (  | 3 Cli  | ck "Reset" in the software.  |  |  |

# 5.3 Replace the ink pump filter





The ink pump filter should be changed every 3 months

- 1 Remove the ink pump power housing;
- Block the ink pipe to avoid backflow;
- $\square$  Remove the ink pipe and the filter;
- $\stackrel{\textstyle 4}{}$  Replace the filter and pay attention to the direction;



5 Stop blocking the ink tube and complete the replacement.

#### 5.5 Replace air tube



Replace the air tube immediately if any damage is found



| 1  | Clo | Close the spray function and close the ink valve                    |  |  |
|----|-----|---|--|--|
| 2  | Pre | Press the emergency stop switch, disconnect the pump power housing; |  |  |
| 2  | Ор  | en the chain;   |  |  |
| 3  | Re  | place the new air tube;   |  |  |
| 4  | Ma  | Mark the airflow direction to avoid the mistake;                    |  |  |
| [5 | Ins | Install and fix the air tube;                                       |  |  |
| (6 | Ins | Install the chain and switch on the printer;                        |  |  |
| 7  | Ch  | Check the negative pressure system see if it is working properly.   |  |  |
|    |     |   |  |  |
|    | Ö   | All air pump power housings must be disconnected before operation   |  |  |

Otherwise it will cause backflow.





There are six kinds of alarms in the equipment, below are the troubleshooting methods for various alarms

| as for various alarms |   |  |
|-----------------------|---|--|
| Alarm type            | One beep, 【Bi】  |  |
| Problem               | Air Pump failure  |  |
| Reason                | The main air pump stops and the backup pump is working      |  |
|                       | First click "reset" in the software to stop the alarm.      |  |
|                       | If the alarm is still on, check if the main pump is working |  |
| Diagnose              | normally and check whether the pump power housing and       |  |
|                       | DC 24V power supply are normal.                             |  |
| Alarm type            | Two beeps, 【Bi-Bi】  |  |
| Problem               | Negative pressure malfunction                               |  |
| Reason                | The negative pressure reached upper/lower limit             |  |
| Diagnose              | Click "reset" in the software                               |  |
| Alarm type            | Three beeps,【Bi-Bi-Bi】                                      |  |
| Problem               | Ink supply system malfunction                               |  |
| Reason                | Sub-tank ink is lower than the alarm level                  |  |



|          | Check if the main tank is starving, if so, add ink. |
|----------|---|
| Diagnose | Check the liquid sensor in sub-tank.                |
|          | Check the ink pump see if it's running normally.    |
|          | Check the ink pump for blockage.                    |
|          | Check the ink supply system for leakage.            |
|          | Check the ink pump filter for blockage              |

| Alarm type | Four beeps, 【Bi-Bi-Bi-Bi】  |
|------------|--|
|            | Data transmission failure  |
| Problem    | Hardware communication malfunction   |
|            | It is normal to hear four alarms occasionally.                               |
| 5.         | If this happens continuous, it may be PCB board or other                     |
|            | hardware malfunction. Please contact your local agent for technical support. |
| Alarm type | Five beeps, 【Bi-Bi-Bi-Bi]  |
|            | Ink supply malfunction   |
|            | Ink backflow to the safety box   |
|            | Close the spray function and the ink valve                                   |
|            | Adjust the negative pressure to -1.0kpa and press the emergency stop button  |
| Problem    | Open the safety box and tap the ink tube to clear the backflow ink           |
|            | Open the top cover of the safety box and clean it with                       |
|            | cleaner  |
|            | Replace the dirty ink tube   |



| Diagnose   | Do not break the ink tube when replacing it. The leakage will cause backflow.  Activate the printer and open the ink valve on the backflow ink box  Drain the ink until the liquid level returns to normal height |  |  |
|------------|---|--|--|
| Alarm type | Six beeps 【Bi-Bi-Bi-Bi-Bi]  |  |  |
| Problem    | Ink supply system malfunction   |  |  |
|            | Main tank starving  |  |  |
|            | Check the main tank level   |  |  |
| Diagnose   | Check the main tank liquid sensor   |  |  |
| 3.000      | Add ink   |  |  |



#### 2. Negative pressure system

#### 2.1 Purge failure

| Continuous press the purge button, but the ink is not coming out from the nozzles |
|---|
| Check the status of the corresponded solenoid valve                               |
| Check if the sub-tank is empty (3 beeps)  |
| Check the positive pressure see if it's normal                                    |
|   |

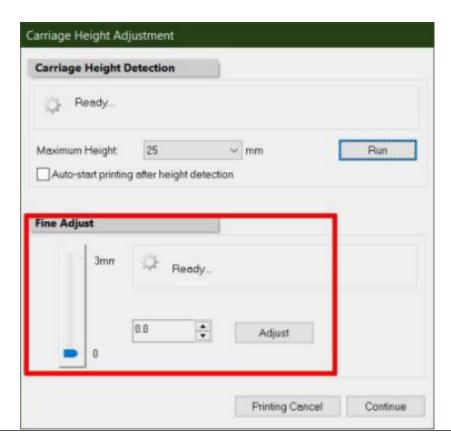
## 3. Printhead accident handling

# 3.1 How to protect the print head from scratch and crash accidents

Must run the height detect before printing each time the media changed

For rough surface and heat sensitive material, besides height detection, need fine tune the height to ensure the print head safety.





For rough surface and heat sensitive material, please adjust the vacuum power and area before printing, this is to get more stable suction.

Since the height sensor is not in the base point, it may never touch the substrate if the medium is in very small size.

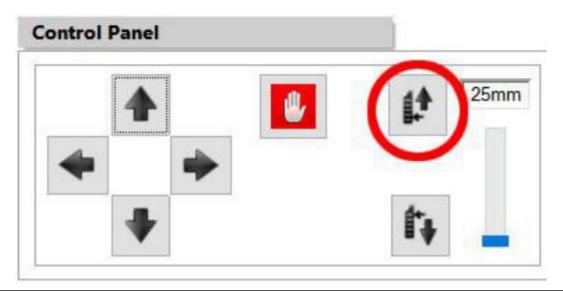
To avoid this from happening under this circumstance, it is recommended to place the media under the sensor to perform height detect then register the media to the printing area.

Do not open the registration device during printing, or it will also scratch the print head. The motor driver will automatically lock down and cause defective printing

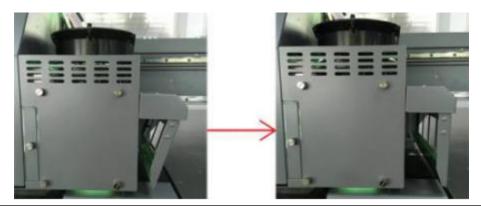


#### 3.2 Print head scratch and crash accident treatment

- 1 Wait for the error message to show on the interface and click ok
- Rise the carriage height as below image showing, remove the media.



Reposition the baffle of the anti-crash on the carriage, as below image



- Click the back to origin button to restore the carriage to the base point.
- 5 Restart printing





It is recommended to print the nozzle test immediately after troubleshooting if there is an accident of rubbing the nozzle surface against the media. Check whether the nozzle is damaged and repair it immediately.



# 4. Carriage motion anomaly

#### 4.1 Error code for FUJI motor driver

When the carriage motion is malfunction, the screen on the driver will show error code.

Please diagnose according to the error code.

| Thease diagnose according to the error code. |            |  |  |  |
|--|------------|--|--|--|
| Nu<br>mber                                   | Code       | Meaning                                | Treatment  |  |
| 1  | oc1 or oc2 | Over current                           | Check and repair power line (U, V, W) wiring   |  |
| 2  | oL1 or oL2 | Overload                               | Check and repair power line (U, V, W) wiring   |  |
| 3  | Hu         | Overvoltage                            | Make sure the power voltage is within the specification range  |  |
| 4  | Fb         | Fuse break                             | Replace the servo amplifier  |  |
| 5  | АН         | Amplifier<br>overheat                  | Keep ambient temperature below 40 $^{\circ}\mathrm{C}$ If there is a heat source near the servo amplifier, move away |  |
| 6  | EH         | Encoder<br>overheating                 | Keeping the surrounding temperature of servo motor under 40 °C  Remove any object that prevents heat release.        |  |
| 7  | LuP        | Main circuit voltage is not sufficient | Confirm and improve the power supply situation. Confirm the power for the supply and adapter                         |  |



| 8  | <sup>-</sup> PoF | Anti-collisi<br>on<br>emergenc<br>y stop | Check the anti-collision device and return to normal  |
|----|------------------|--|---|
| 9  | ⁻Pn0             | Registration device is on                | Check and restore the media registration device to normal state   |
| 10 | =Pot             | Y axis<br>base point<br>display          | If Y displays this code when it is not at the origin, check whether the photoelectric switch is working properly          |
| 11 | =PP1             | Pulse<br>column input<br>in operation    | The x-direction servo drive will display in normal state  The y-direction drive will display when it is not at the origin |

#### 4.2 Carriage stuck during printing

# During printing, the carriage is detained too long on both edges. Diagnose When the printing data is too large, it will easily slow down the reading for RIP and printing data. Please start printing after the RIP process finished. Install anti-virus software, check for virus in the flash driver every time copying the image with it. Scan the PC for virus regularly.

#### 4.3 Device busy alert



#### **Description**

The software alert for error, interface shows below warning:

"Device is busy, please check the media location plate, raster reader and motor driver, try again."

#### Diagnose

- 1. The anti-collision device is triggered.
- 2. The raster encoder crash with obstacles and changed position, causing data reading failure. Adjust the raster encoder to the right position.
  - 3. Optical fiber cable wear out, please replace the fiber cable.



# 4.4Height detect anomaly

| D   | Description  |  |  |
|---|--|--|--|
| When performing height detection, the carriage can lift up but can't go down. |  |  |  |
| D   | Diagnose   |  |  |
| 1   | The height detect components are dirty cause high friction and the |  |  |
|   | probe cannot go down. Please clean the components.                 |  |  |
| 2   | The height detect switch break down. Replace the height detect     |  |  |
|   | switch.  |  |  |

# 4.5Abnormal printing quality

| Description                | Diagnose   |
|----------------------------|--|
| Obvious horizontal bending | Perform horizontal nozzle registration calibration |
| Fuzzy printing quality     | Perform offset calibration                         |



| Fuzzy printing quality            | Check the print head height see if it is too high, normally should be 2mm from the nozzle to substrate surface.      |
|-----------------------------------|--|
|                                   | Clean the print head surface, redo calibration   |
| Printing color darker or lighter. | Adjust colors in the job editor, if the color is darker, lower the overall ink limit 10-30. If the color is lighter, |
| If the brightness is not          | raise the overall ink limit 10-30.   |
| enough(or normally called         | Perform offset calibration  Check the print head vertical calibration  |
| noise), when printing vibrant,    | Change the spreading type: Switch between FX-2 and   |
| the color transition part         | J-STOCH, compare the performance.  |
| showing missing line or           |  |
| regular bending.                  |  |
| Printed border lines are not      | Re-do the calibration  |
| straight                          | Perform the horizontal nozzle registration Offset calibration  |

### 5. Tools and attribute



|   | Tool  | Function                                    |
|---|---|---|
|   | Diagonal pliers                                   | Cut off the ink tube and air tube           |
|   | Ink valve spanner                                 | Open and close the ink valve                |
|   | Monkey wrench                                     | Adjust the level of the machine             |
|   | Allen Key   | Adjust the inner hexagon screw              |
|   | Phillips<br>screwdriver<br>Slotted<br>screwdriver | Adjust the cross and slotted screws         |
|   | Cleaner   | Clean the ink path and printhead            |
|   | Clean cloth                                       | Wipe the printhead                          |
|   | Alcohol   | Cleaning equipment                          |
|   | Rag   | Cleaning equipment                          |
| 0 | Rubber gloves                                     | Protect the operator when wiping the nozzle |
| 1 | Glue gun  | Lubricating motion unit                     |
| 2 | Lithium base grease                               | Lubricating motion unit                     |
| 3 | Plastic injector                                  | Use when installing sprinkler head          |

#### Instruction for HT3200 conveyor belt rectify

#### I. Rectifying use guide:

- 1. This instruction only refer to HT3200B/C/B3200 models;
- 2. Please read this instruction carefully before power on the machine.

#### II. Tool

Allen Key

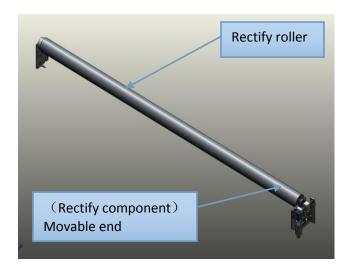
#### III. Operation guide

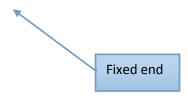
No matter large format belt or conveyor belt, it will run stable if both edges share the same tightness. If not, it will run from the tight end to the loose end, this is what called deviation.

Based on this phenomenon, we equipped the HTB3200 conveyor belt with rectifying device to avoid deviation during operating. The explanations and guide are as below:

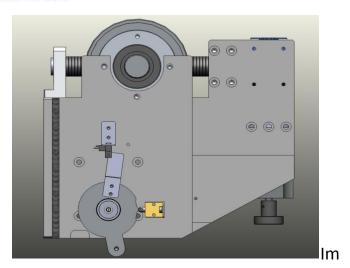
#### 1. How to realize rectifying

According to the deviation principle, the machine is equipped with a rectify roller. This roller is fixed in one end as well as another movable end. The structure allows the movable end to move left and right. (See image 1).









age 1

When the belt on the rectify roller movable side is loose, it will move left to press the belt on this side to balance the tension of both sides of the conveyor belt. In contrary situation, the rectify roller will move right to leave the belt on this side, the tension of both sides will be balanced.

The conveyor belt will not get deviation when both ends has the same tension(See image 2)

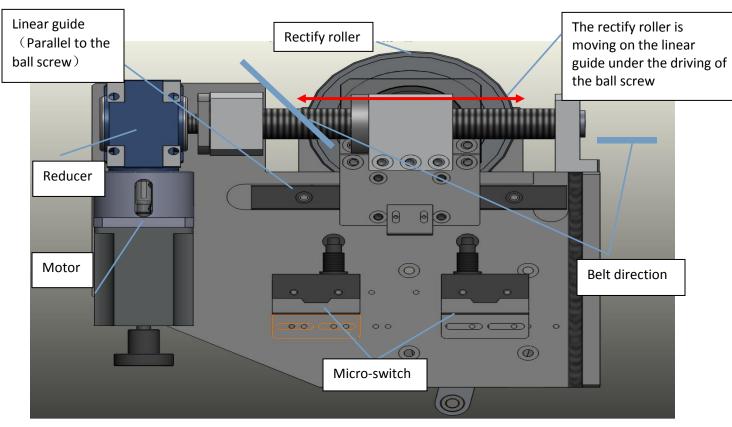




Image 2

### 2.Operation

The conveyor belt rectifying device is with simple and tight design, during the machine operation, it is user-friendly for customers. After the conveyor belt assembled, the belt tightness can be adjusted by the adjusting screw on both sides of the rectify roller (See image 3 and 4), this adjustment will be finished by professional technician before the printer been sent out the factory, normally the customer won't need to adjust again.

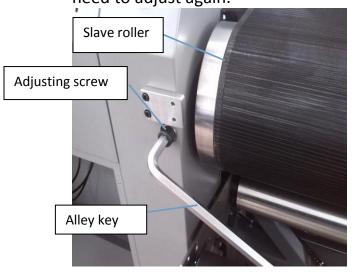


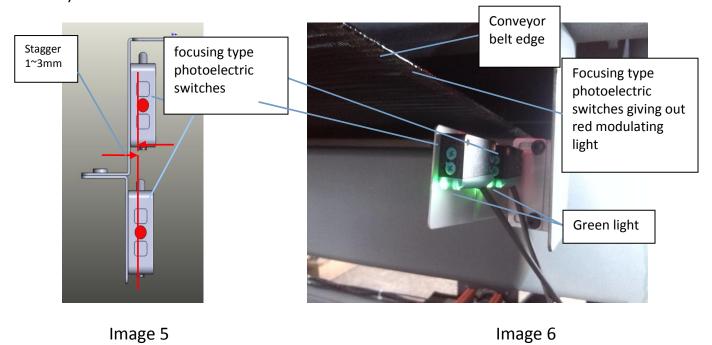


Image 3 (Left end)

Image 4 (Right end)



During the machine operation, there are 2 focusing type photoelectric switches giving out red modulating light pointing the conveyor belt edge. Through the control program, the motors controlling the ball screw will run in different direction according to the signal and move the rectify roller to the left and right. (See image 5 and 6)



The 2 focusing type photoelectric switches are staggered 1-3mm against the belt moving direction when assembling them. This will maintain the belt shift within this range. This was done in the factory, customers don't need to change or move the position of these 2 switches. (See image 5 and 6)

There a 3 status for the 2 photoelectric switches: ①Both 2 green lights are off ②One green light is on, another off ③ Both 2 green lights are on (See image 6);

When both green lights are on for 10s, the rectify roller will move to the right side or in the right position; when both lights are off for 10s, the rectify roller will move to the left or in the left position. When one light is on while another one off, the rectify roller will not move. (See image 7)



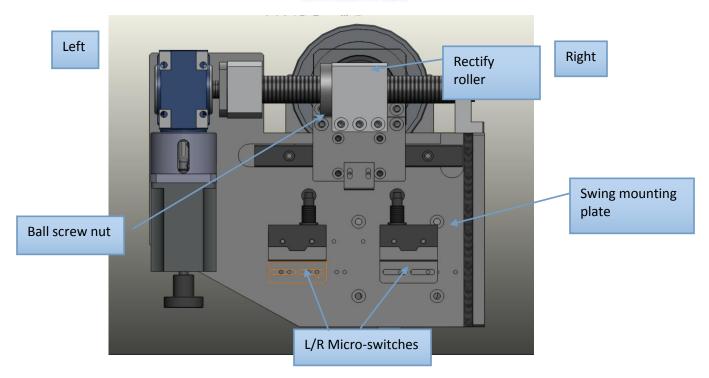


Image 7

When the rectify roller is moving right or left, the swing mounting plate in the bottom will trigger one of the micro-switches, the servo motor will stop working, the rectify roller will stay in right or left and stabilize the belt movement continuously. (See image 6)

Only when both green lights on the focusing photoelectric switches are on or off, and above rectify device is not able to correct the conveyor belt deviation, can we adjust the belt tightness through the adjusting screws on both sides of the slave roller. When adjusting them, use a Allen key to tighten both sides. Give even strength for both sides in the beginning, manually control the tension. (See image 3 and 4)

Start up the machine, observe the belt swinging status. A. the rectify device is in the right limit, if the belt is moving left (Reference from the backside of the machine), means the rectify process is correct. If the belt is shifting fast, tighten the left a bit or loose the right side a bit. If the belt is shifting to the right side, this means the rectify is wrong, need to tighten the right side and loose the left side until the belt shifting to the left side. B. Same principle when the situation is in contrary.

When the rectify device is in control of the belt, continue to adjust slightly with the alley key until the belt deviation is in sufficient control.



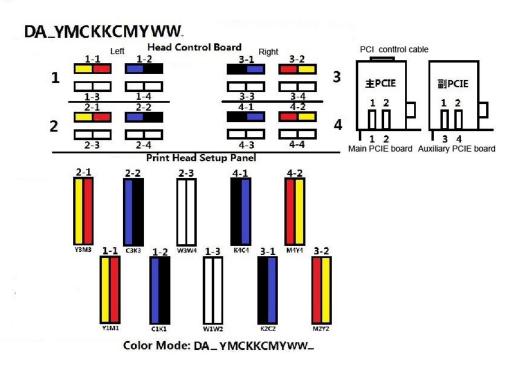
# IV Technical requirements

- 1. Test run the machine each time start up the machine, observe carefully for anomaly shaking and noise. After confirmation, begin working.
- 2. Observe for the photoelectric switches and micro-switches, they should be giving the right signal.



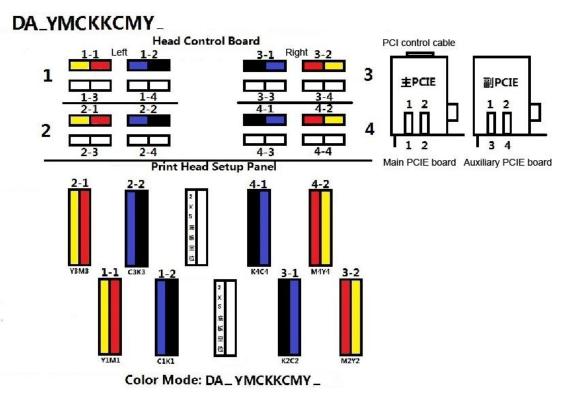
# Cable diagram of HT3200D head configuration(2X5)

Mode:DA\_YMCKKCMYWW

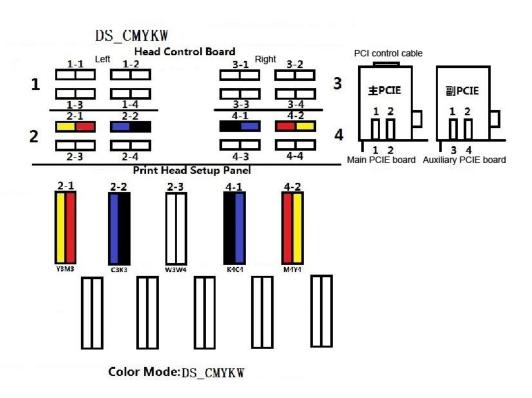


Mode:DA\_YMCKKCMY\_



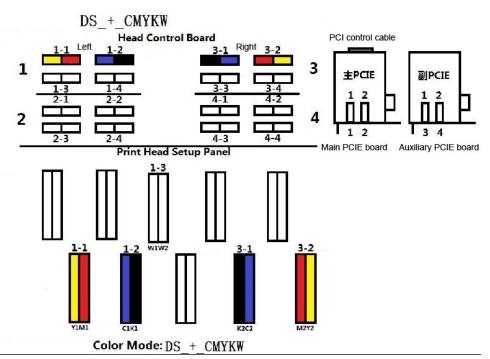


Mode:DA\_CMYKW



Mode:DA\_+\_CMYKW





Mode:DA\_YMCKKCMYWW

Mode:DS\_CMYK

